

Engineering Self-Adaptive Software Systems with Runtime Models

Seminar on QoS Attributes in Service- and Cloud-based Systems



SCHLOSS DAGSTUHL

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Motivation

- Need to continuously change software
 - Lehman's laws of software evolution [Lehman and Belady, 1985]
 - Software aging [Parnas, 1994]

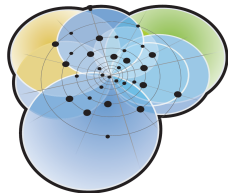
⇒ **Software evolution and maintenance**

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⇒ **Software evolution and maintenance**

- Software systems that are...
 - self- or context-aware
 - mission-critical
 - ultra-large-scale (ULS)
 - ...

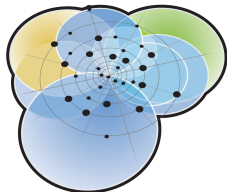


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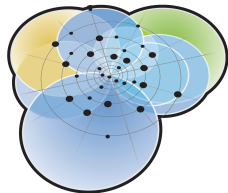
*“Evolution in ULS systems will rarely occur in discrete, planned steps in a closed environment; instead it will be continuous and dynamic. The rules for continuous evolution must therefore be built into ULS systems [...] so that they will be [...] able to cope with dynamically changing environments without constant human intervention. Achieving this goal requires research on **in situ control, reflection, and adaptation** to ensure continuous adherence to system functional and quality-of-service policies in the context of rapidly changing operational demands and resource availability.”*
[Northrop et al., 2006, p.33]

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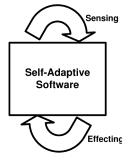
⇒ **Self-adaptive Software** [Cheng et al., 2009, de Lemos et al., 2012]

⇒ **Autonomic Computing** [Kephart and Chess, 2003]

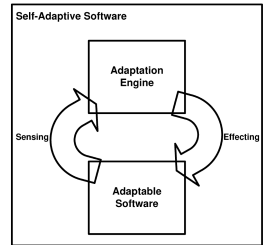
Remark: Co-existence of evolution/maintenance and self-adaptation

Engineering Self-adaptive Software

- (1) Cost-effective development
- (2) Reflection capabilities
- (3) Making feedback loops explicit
- (4) Flexible (runtime) solutions



Internal Approach



External Approach

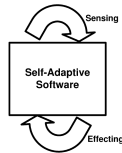
[Salehie and Tahvildari, 2009, p.14:15]

Related approaches, e.g.:

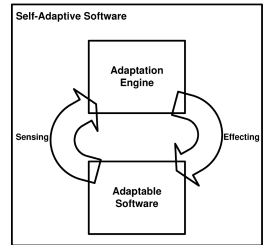
- *Rainbow* [Garlan et al., 2004] : (1), (2), (3), (4)
- *J3 Toolsuite* [Schmidt et al., 2008] : (1), (2), (3), (4)

Engineering Self-adaptive Software

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External Approach

[Salehie and Tahvildari, 2009, p.14:15]

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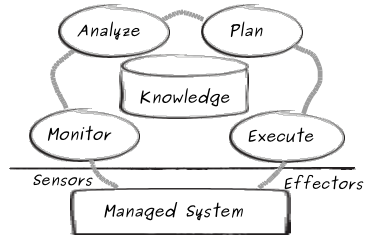
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Models at runtime for engineering adaptation engines: (1)-(4)

Adaptation Engine

Feedback Loop consisting of

- **Adaptation steps**
Monitor, Analyze, Plan, Execute
- **Knowledge**
about the managed system and its context



[Kephart and Chess, 2003]



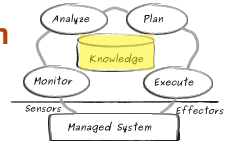
General goal: leverage MDE techniques and benefits to the runtime environment [France and Rumpe, 2007, Blair et al., 2009]

⇒ **Models@run.time for adaptation steps & knowledge**

Knowledge

Models causally connected to the running system

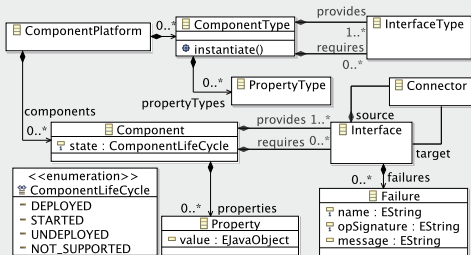
- Typically, **one** model is employed (often an architectural model emphasizing one concern)
(cf. related work in [Vogel and Giese, 2010])
- Simultaneous use of multiple runtime models
- **abstraction levels** — PSM vs. PIM (solution vs. problem space)
 - PSM: easier to connect to the running system
 - PIM: easier to use by adaptation steps
- **concerns** — failures, performance, architectural constraints, . . .
- ⇒ Different views on a running system
- ⇒ **reflection capabilities** enabled and used by adaptation steps



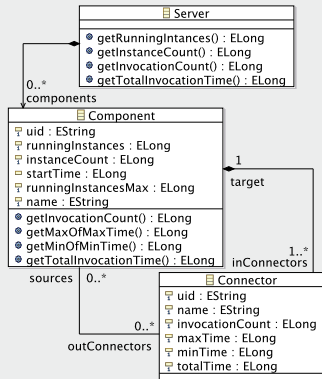
Knowledge — Reflection Models

Metamodels for PIMs

Failures

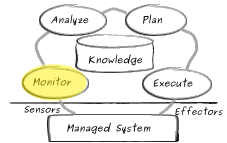


Performance



Monitor

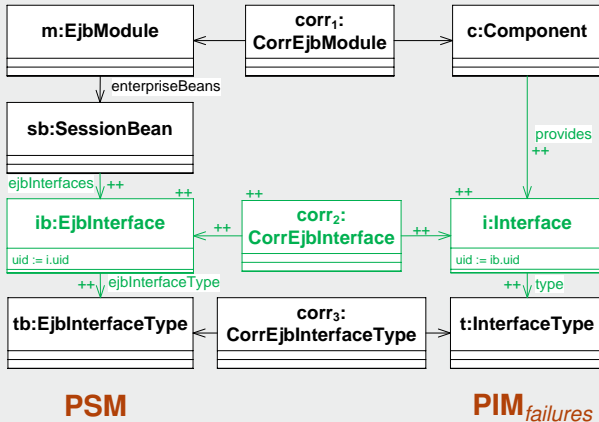
Synchronizing changes in the system to the reflection models



- Keeping runtime models up-to-date and consistent to each other
- Sensors (instrumentation): management APIs
- **Incremental**, event-driven updates: System \rightarrow PSM
(manually implemented adapter)
- **Incremental** model synchronization: PSM \rightarrow PIM₁, PIM₂, ...
(Model synchronization engine based on Triple Graph Grammars (TGG))

Monitor — TGG Rules

TGG rule for PSM \rightarrow PIM_{failures}



- Overall, 11 rules for PSM \rightarrow PIM_{failures}

Monitor — Development costs

generated code from TGG rules

PIMs	Proposed solution			Batch LOC
	#Rules	#Nodes/Rules	LOC	
Simpl. Architectural Model	9	7,44	15259	357
Performance Model	4	6,25	5979	253
Failure Model	7	7,14	12133	292
Sum	20		33371	902

- **Proposed solution** — **incremental** synchronization
 - System → PSM: 2685 LOC for the reusable adapter
 - PSM → 3 PIMs: 20 TGG rules (generated >33k LOC)
- **Batch** — creates PIMs directly from scratch (**non-incremental**)
 - 902 LOC (\approx 20 TGG rules)
- Declarative vs. imperative approaches

Remark: done for slightly different metamodels than shown here

Monitor — Performance

Size	Proposed Solution						Batch
	n=0	n=1	n=2	n=3	n=4	n=5	
5	0	163	361	523	749	891	8037
10	0	152	272	457	585	790	9663
15	0	157	308	472	643	848	10811
20	0	170	325	481	623	820	12257
25	0	178	339	523	708	850	15311
System → PSM	0%	92.8%	94.1%	95.6%	95.2%	96.3%	-
PSM → 3 PIMs	0%	7.2%	5.9%	4.4%	4.8%	3.7%	-

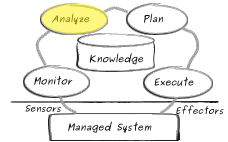
[ms]

- **Size:** number of deployed beans
- Structural monitoring through event-driven sensors
- Processing **n** events and invoking **once** the model synchronization engine

Remark: done for slightly different metamodels than shown here

Analyze

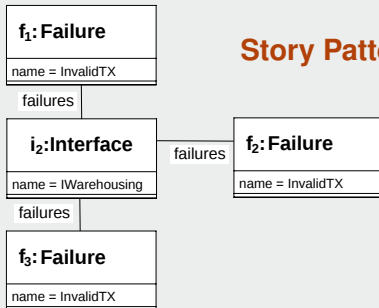
Analyzing the running system based on reflection models (PIMs)



- Identifying needs for adaptation (reactively)
- Structural checks expressed in **Story Patterns**
(Story Pattern and Story Diagram Interpreter)
- Under certain conditions, **incremental** execution of Story Patterns
- Constraints expressed in the **Object Constraint Language (OCL)**
(Existing engine from the Eclipse Model Development Tools)
- Model-based analysis techniques

Analyze — Evaluation Models

Identifying failures or violations of architectural constraints

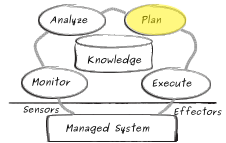


OCL expression

```
if self.name = 'TShop'
then self.components.size() <= 1
else true
endif
```

Plan

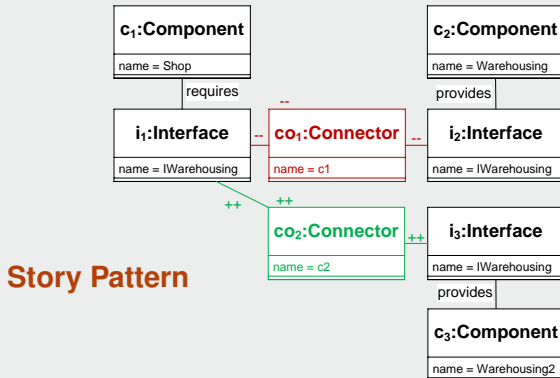
Planning adaptations based on analysis results



- Changing reflection models (PIMs) (and in the end the system)
- **Story Patterns** defining in-place transformations (Story Pattern and Story Diagram Interpreter)
- Under certain conditions, **incremental** execution of Story Patterns
- **OCL expression** to check and manipulate models (Existing engine from the Eclipse Model Development Tools)

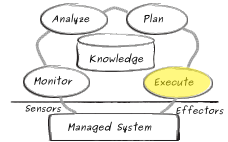
Plan — Change Models

Switching connections between components



Execute

Synchronizing changes of reflection models to the system: PIMs → PSM → System

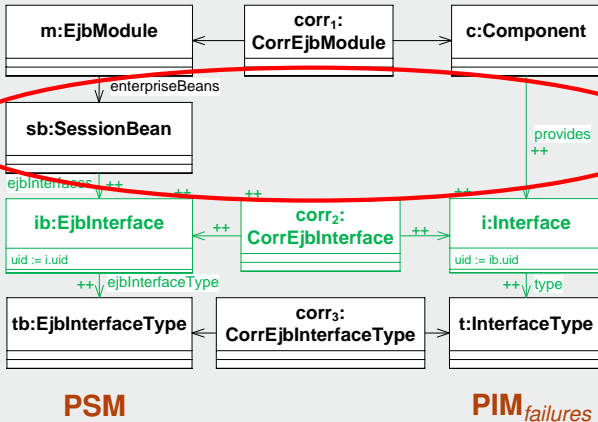


- PIM → PSM
 - **Incremental** model synchronization: same rules as for monitoring due to bidirectionality of TGG
 - Story Patterns for default creation patterns in refinement transformations (**Factories**)
- PSM → System
 - Observing PSM changes performed by the model synch. engine
 - Incrementally enacting these changes through effectors (management APIs)

Execute — TGG Rules

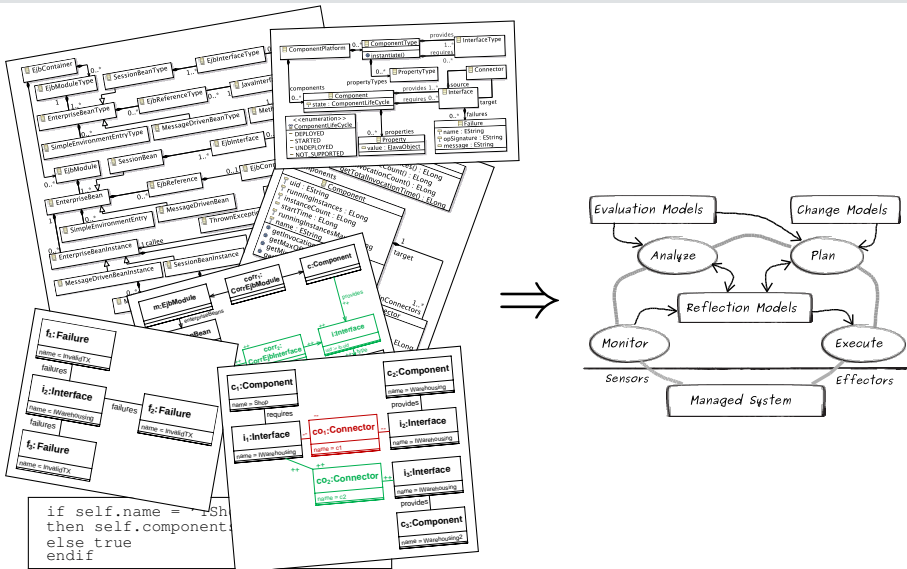
TGG rule for PSM \leftrightarrow PIM_{failures}

Factory
required!



- Overall, 11 rules and 1 factory for PSM \leftrightarrow PIM_{failures}

Interplay of all those models?



Specifying and executing feedback loops

Specification — Modeling language

- Capturing the interplay of multiple runtime models
[Vogel et al., 2010, Vogel et al., 2011]
- Making feedback loops **explicit** in the design of self-adaptive systems [Müller et al., 2008, Brun et al., 2009]

Execution — Model interpreter

- **Flexible** solutions and structures for feedback loops
 - Adaptive control [Kramer and Magee, 2007] \Rightarrow multiple loops
 - Uncertainty [Esfahani and Malek, 2012]
 - State-of-the-art frameworks often prescribe static solutions to single feedback loops (e.g., [Garlan et al., 2004, Schmidt et al., 2008])

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Executable Megamodels

Megamodels

Definition (Megamodel)

A *megamodel* is a model that contains models and relations by means of model operations between those models.

In general:



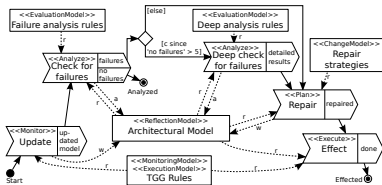
Model-Driven Architecture (MDA) example:



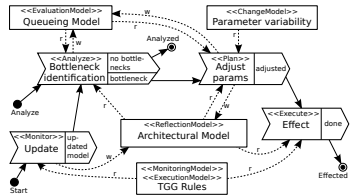
- Research on model-driven software development (MDA, MDE)
[Favre, 2005, Bézivin et al., 2003, Bézivin et al., 2004, Barbero et al., 2007]
- “Toward Megamodels at Runtime” [Vogel et al., 2010]

Modeling Interacting Feedback Loops

Self-repair

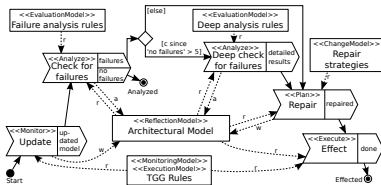


Self-optimization

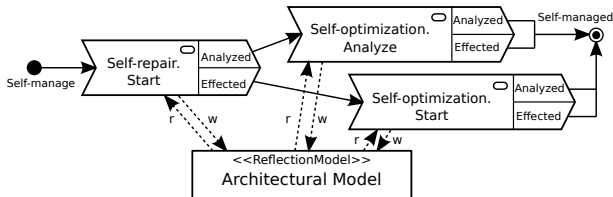
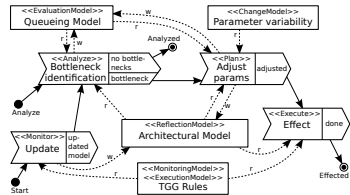


Modeling Interacting Feedback Loops

Self-repair



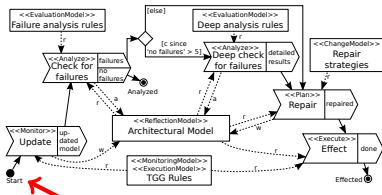
Self-optimization



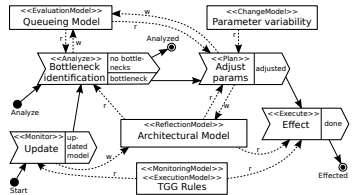
One solution: Linearizing Complete Feedback Loops

Modeling Interacting Feedback Loops

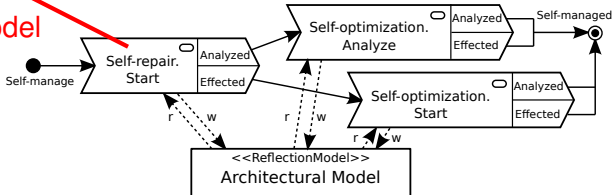
Self-repair



Self-optimization



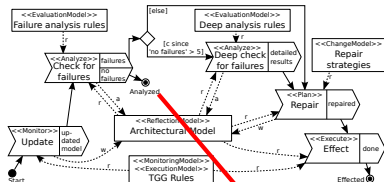
Complex model operations



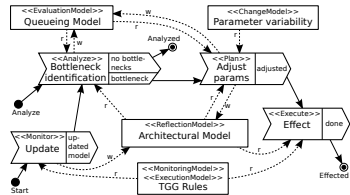
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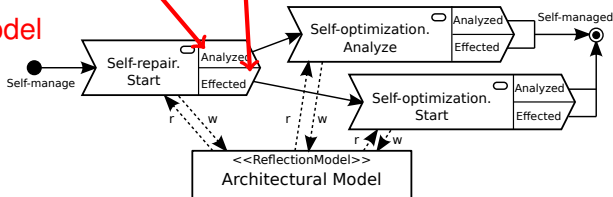
Self-repair



Self-optimization



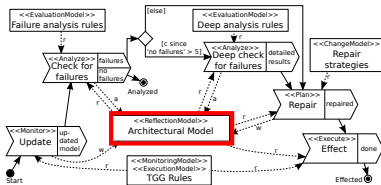
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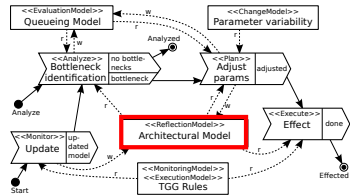
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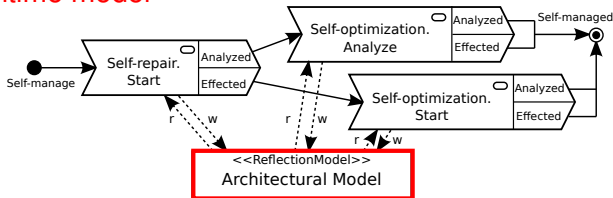
Self-repair



Self-optimization



Shared runtime model



One solution: Linearizing Complete Feedback Loops

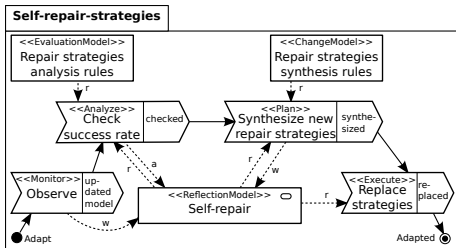
Modeling Hierarchies of Feedback Loops

*Layer*₀

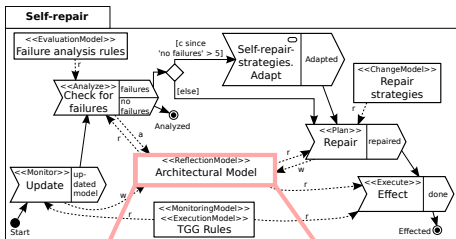


Modeling Hierarchies of Feedback Loops

Layer₂



Layer₁



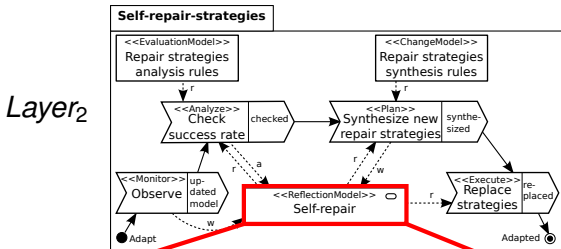
Layer₀



Causal connection

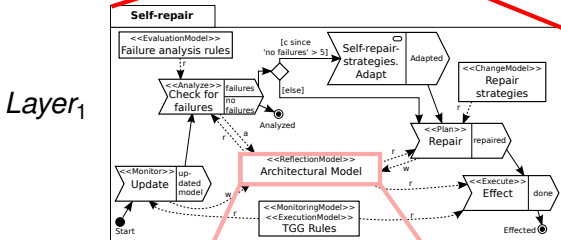
- sensors + effectors required
- implementation efforts!

Modeling Hierarchies of Feedback Loops



Layer₂ directly uses the megamodel of Layer₁

- no specific sensors and effectors required
- adapts the models or control flow of the Layer₁ megamodel
- interpreter (flexibility)!



Causal connection

- sensors + effectors required
- implementation efforts!

Layer₀



Conclusion

Models at runtime

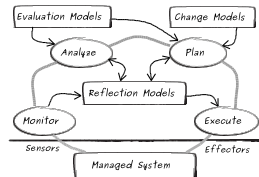
- Adaptation steps and knowledge
- Single and multiple feedback loops

Discussion

- (1) Cost-effective development
 - (2) Reflection capabilities
 - (3) Making feedback loops explicit
 - (4) Flexible (runtime) solutions
- ... while being runtime efficient (incremental, on-line techniques)

Interests:

- Techniques, algorithms, models, and tools for QoS attributes
- Software architecture ↔ multiple QoS attributes



Further Reading

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Used Sources

- Slide 1: Dagstuhl figure from <http://www.dagstuhl.de/>.
- Slide 2: Ultra-large-scale systems [Northrop et al., 2006].