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Sentence Annotation: Semantic Role Labeling

Question Answering
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Automatic Labeling of Semantic Roles

Agenda

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- Frame Semantics
- Goals
- Approach
- Discussion

What are Semantic Roles?

Frame Semantics

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- Linguistic theory
 - Knowledge of context → word can be (partially) understood

Jim flew his plane to Texas.

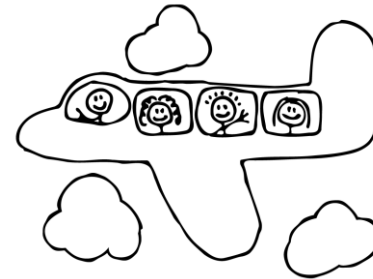
Alice destroys the item with a plane.

Frame Semantics

6

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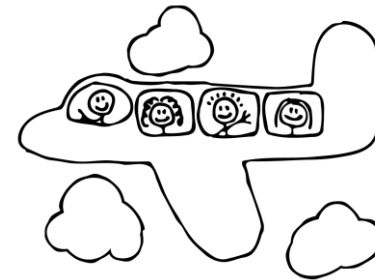
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Frame Semantics

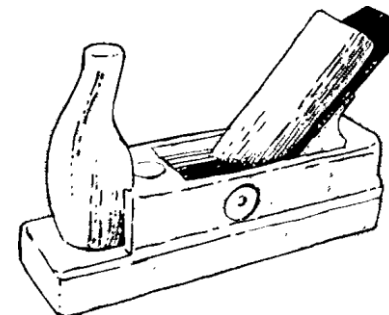
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- Linguistic theory
 - Knowledge of context → word can be (partially) understood

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Alice destroys the item with a plane



Frame Semantics – Semantic Frames

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- Semantic Frame: collection of facts that specify “characteristic features, attributes, and functions of a denotatum, and its characteristic interactions with things necessarily or typically associated with it” (Keith Alan, Natural Language Semantics)
- Target words invoke a semantic frame

Jim flew his plane to Texas.

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Frame Semantics – Semantic Frames

9

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Frame Semantics – Semantic Frames

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Jim flew his plane to Texas.

Operate_vehicle

Alice destroys the item with a plane.

Frame Semantics – Semantic Frames

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Frame Semantics – Semantic Frames

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Jim flew his plane to Texas.

Operate_vehicle

Alice destroys the item with a plane.

Destroying

Frame Semantics – Semantic Roles

13

- Semantic Role: defined part of a Semantic frame
- Can be assigned to constituents of a sentence

Jim flew his plane to Texas.

Operate_vehicle

Alice destroys the item with a plane.

Destroying

Frame Semantics – Semantic Roles

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- Semantic Role: defined part of a Semantic frame
- Can be assigned to constituents of a sentence

<p>Jim flew his plane to Texas.</p>	Operate_vehicle
<p>Driver Vehicle Goal</p>	

<p>Alice destroys the item with a plane.</p>	Destroying
--	------------

Frame Semantics – Semantic Roles

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- Semantic Role: defined part of a Semantic frame
- Can be assigned to constituents of a sentence

<p>Jim flew his plane to Texas.</p>	Operate_vehicle
<p>Driver Vehicle Goal</p>	

<p>Alice destroys the item with a plane.</p>	Destroying
<p>Destroyer Undergoer Instrument</p>	

Frame Semantics - Range

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- Wide range possible

Abstract

- Agent
- Patient
- Experiencer
- Source
- ...



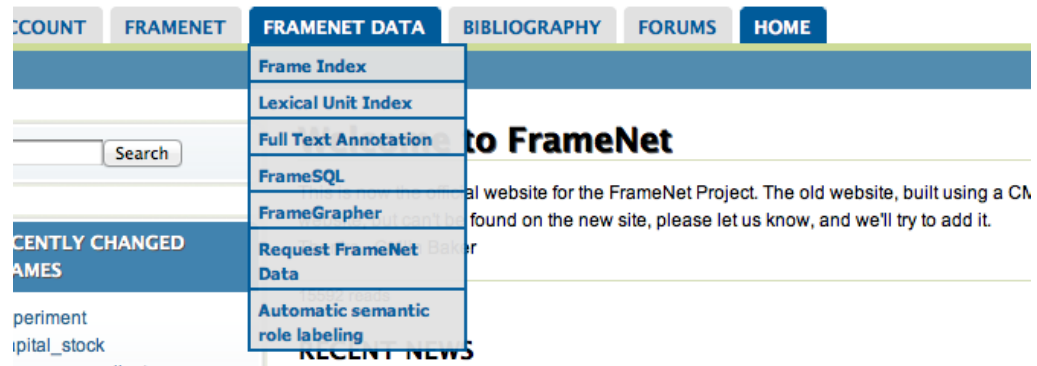
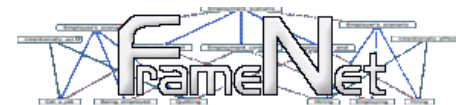
Domain Specific

- Buyer
- Depart_Time
- Dest_Airport
- Winning_Team
- ...

Frame Semantics – FrameNet

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- Dictionary based on semantic frames
 - Uses British National Corpus
- Contains large set of:
 - Example sentences
 - Target words (“Lexical Units”)
 - Semantic frames (grouped in domains)
 - Associated roles (frame elements)
- Manually annotated

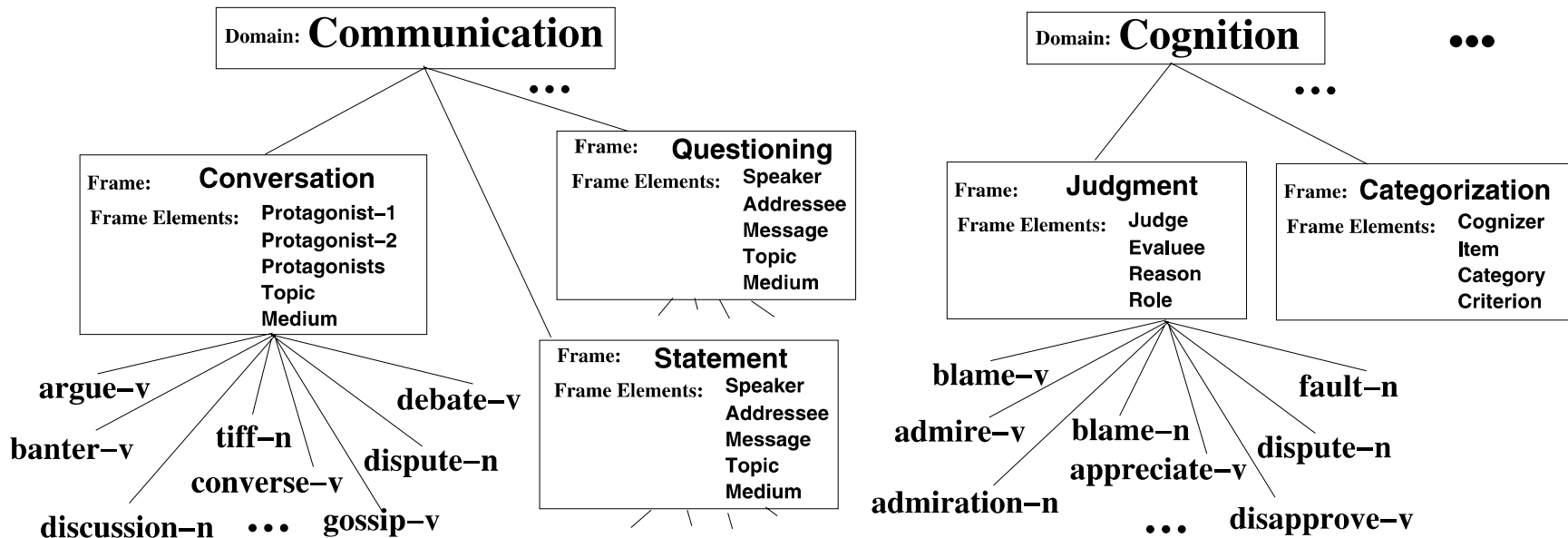


<https://framenet.icsi.berkeley.edu>

Frame Semantics – FrameNet

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- Example



Goals

Goals – Usage in QA

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- How can semantic roles help in QA?
- → analyze question → analyze possible answer sentences → find equalities between frames

Goals – Usage in QA

21

- How can semantic roles help in QA?
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Q: Who invented the first computer mouse?

Goals – Usage in QA

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- How can semantic roles help in QA?
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Q: Who invented the first computer mouse?

[...] The trackball was invented by Tom Cranston, Fred Longstaff and Kenyon Taylor working on the Royal Canadian Navy's DATAR project in 1952. Independently, Douglas Engelbart at the Stanford Research Institute invented the first computer mouse in 1963 [...]

Goals – Usage in QA

23

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Goals – Usage in QA

24

- How can semantic roles help in QA?
- → analyze question → analyze possible answer sentences → find equalities between frames

Q: Who invented the first computer mouse?
 Cognizer New_idea

[...] The trackball was invented by Tom Cranston, Fred Longstaff and Kenyon Taylor working on the Royal Canadian Navy's DATAR project in 1952. Independently, Douglas Engelbart at the Stanford Research Institute invented the first computer mouse in 1963 [...]

Goals – Usage in QA

26

- How can semantic roles help in QA?
- → analyze question → analyze possible answer sentences → find equalities between frames

Q: Who first computer mouse?

Cognizer

New_idea

[...] The trackball ^{New_idea} ^{Cognizer} Tom Cranston, Fred Longstaff and Kenyon Taylor working on the Royal Canadian Navy's DATAR project in 1952. Independently, Douglas Engelbart at the Stanford Research Institute invented the first computer mouse in 1963 [...]

Goals – Usage in QA

27

- How can semantic roles help in QA?
- → analyze question → analyze possible answer sentences → find equalities between frames

Q: **Who** invented the **first computer mouse?**

Cognizer

New_idea

[...] The **trackball** was invented by **Tom Cranston, Fred Longstaff and Kenyon Taylor** working on the Royal Canadian Navy's DATAR project in 1952. Independently, Douglas Engelbart at the Stanford Research Institute invented the first computer mouse in 1963 [...]

Goals – Usage in QA

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- How can semantic roles help in QA?
- → analyze question → analyze possible answer sentences → find equalities between frames

Q: Who invented the first computer mouse?

Cognizer

New_idea

[...] The trackball was invented by Tom Cranston, Fred Longstaff and Kenyon Taylor working on the Royal Canadian Navy's DATAR project in 1952. Independently, Douglas Engelbart at the Stanford Research Institute invented the first computer mouse in 1963 [...]

Goals – Usage in QA

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- How can semantic roles help in QA?
- → analyze question → analyze possible answer sentences → find equalities between frames

Automatic Labeling of Semantic Roles

[...] The trackball was invented by Tom Cranston, Fred Longstaff and Kenyon Taylor working on the Roy **Cognizer** n Navy's DATAR project in 1952. Independently, Douglas Engelbart at the Stanford Research Institute invented the first computer mouse in 1963 [...]

New_idea

Approach

Approach – Basic Idea

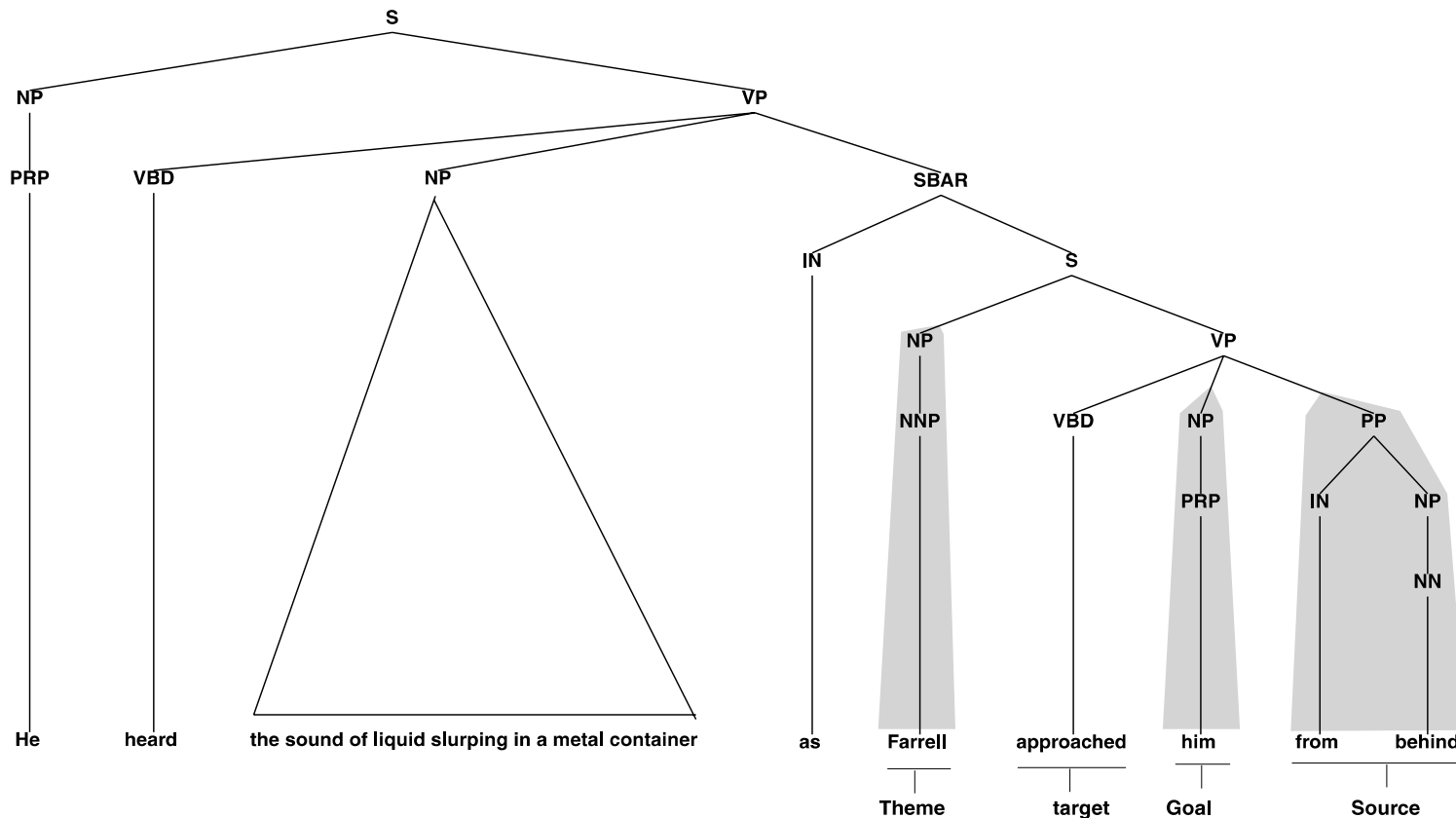
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- Statistical classifier
 - Assigns roles based on probabilities
 - Probabilities calculated / derived from features
- FrameNet data
 - 10% for testing, 10% for tuning, 80% for training
- Given data:
 - Sentence / clause
 - Target word
 - Frame
 - (role boundaries)

Approach – Features

33

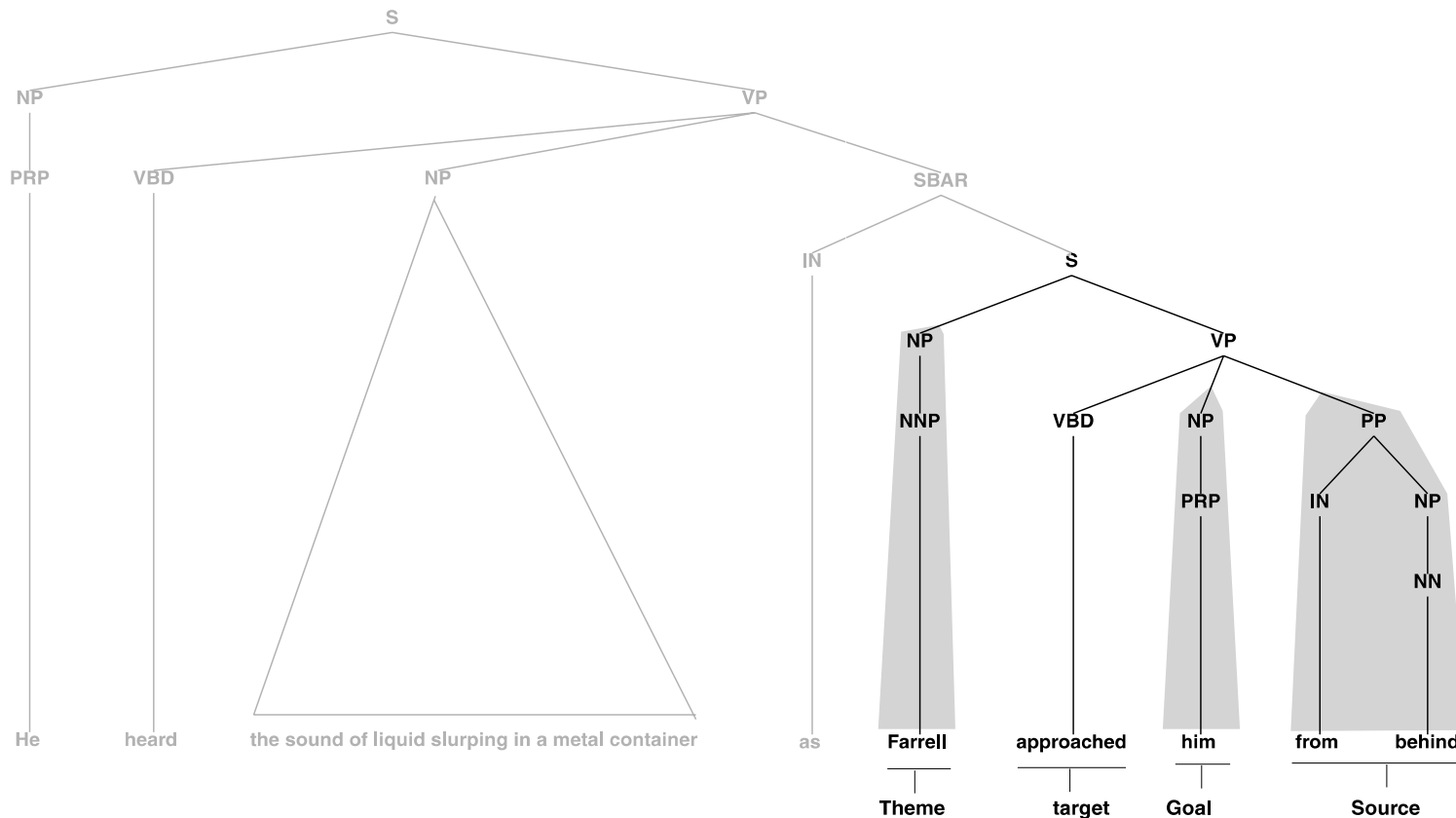
- “Collins” Parser for generating a parse tree
- Used for the derivation of some features



Approach – Features

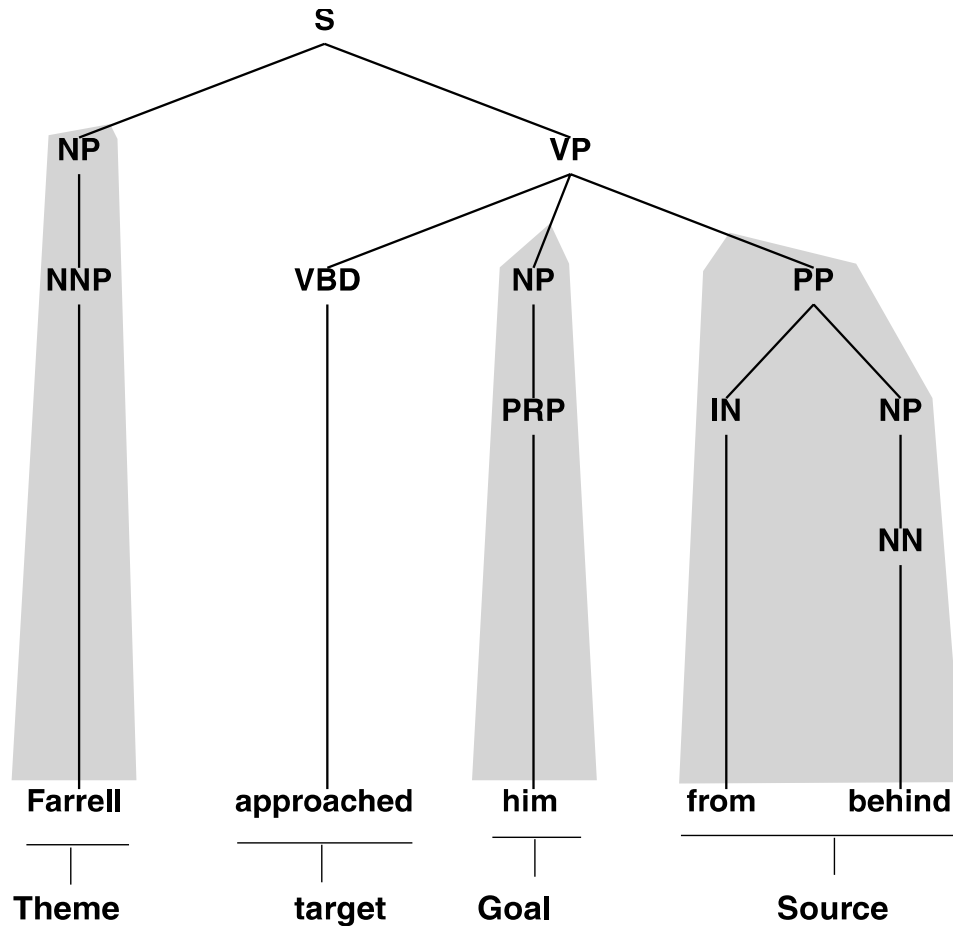
34

- “Collins” Parser for generating a parse tree
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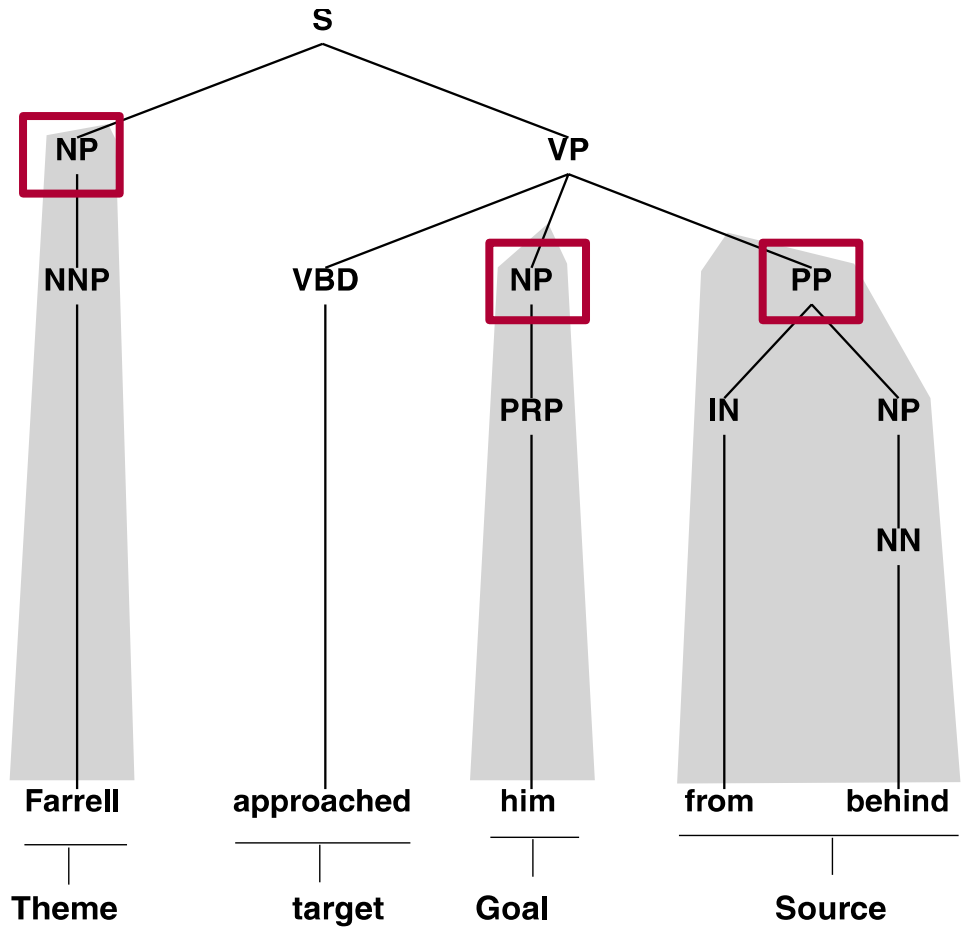
Approach – Features – Phrase type

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Approach – Features – Phrase type

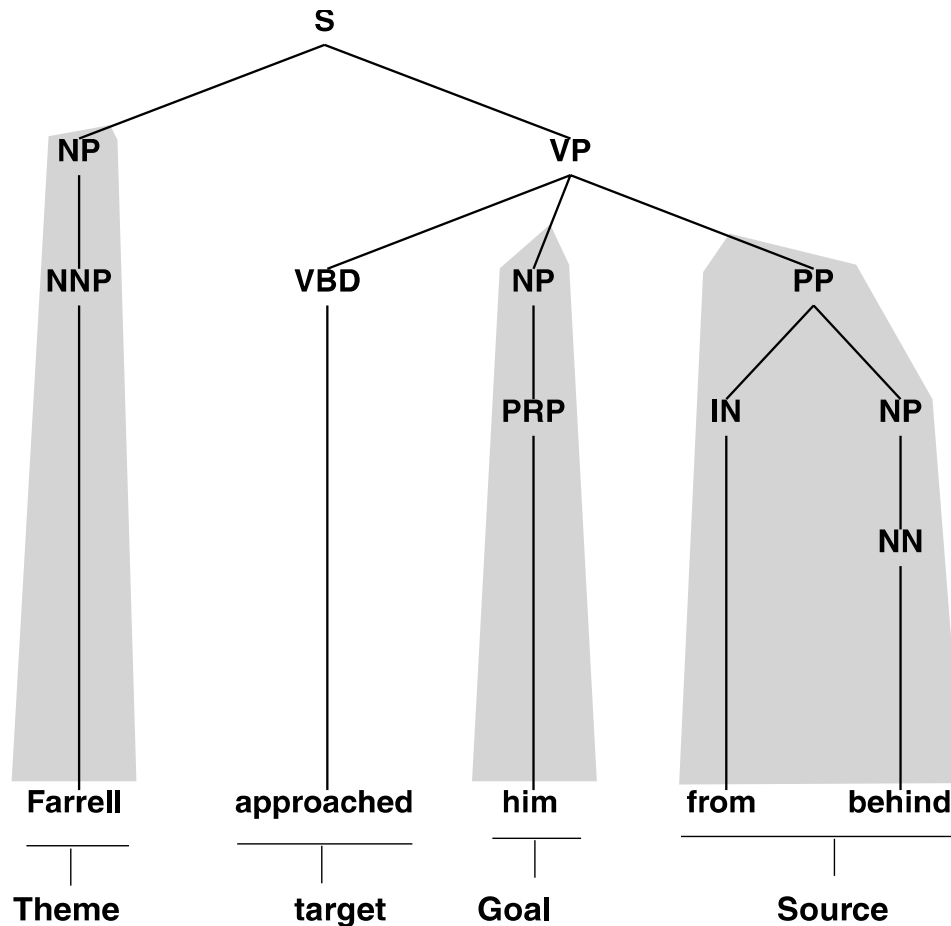
36



- "Farrell" → NP
- "him" → NP
- "from behind" → PP

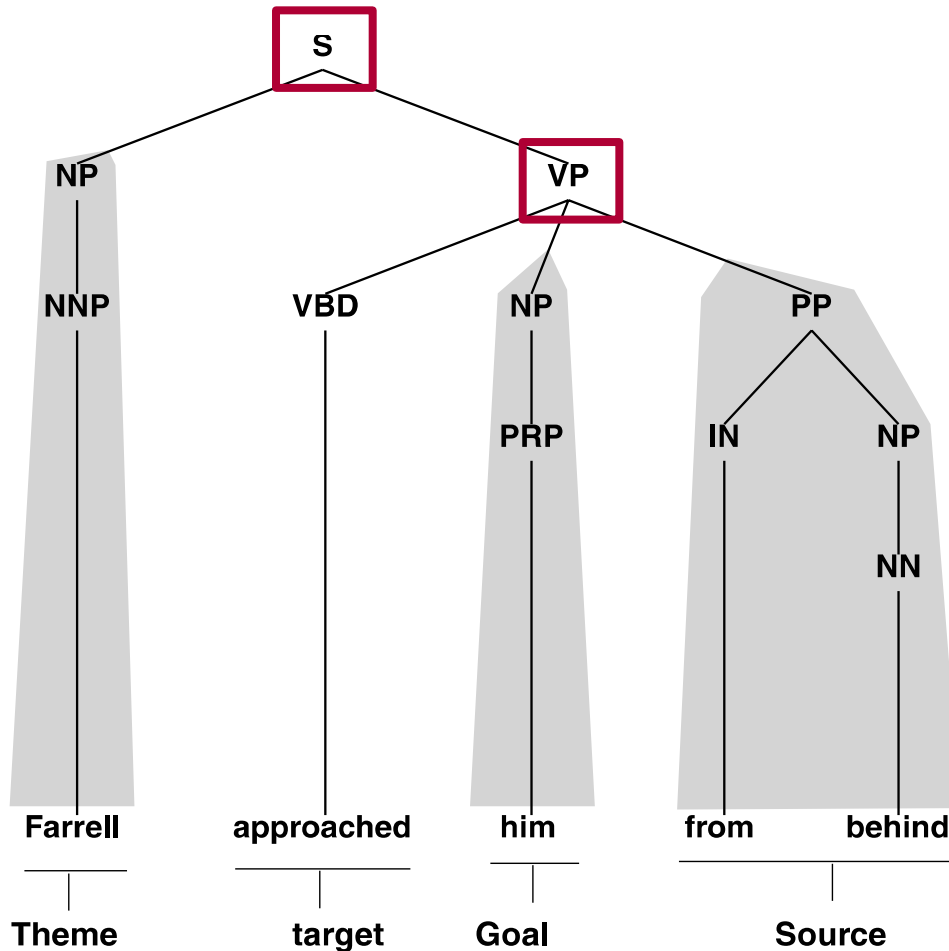
Approach – Features – Governing Category

37



Approach – Features – Governing Category

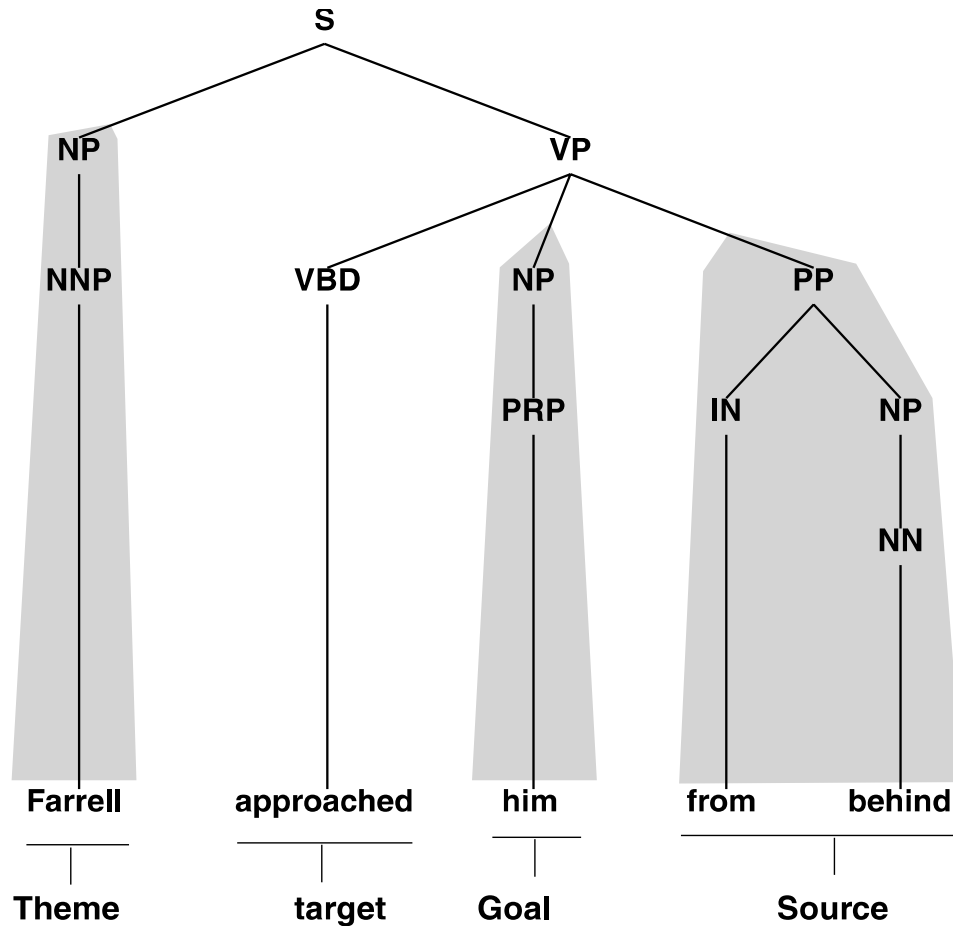
38



- “Farrell” → S
- “him” → VP
- “from behind” → *nothing*

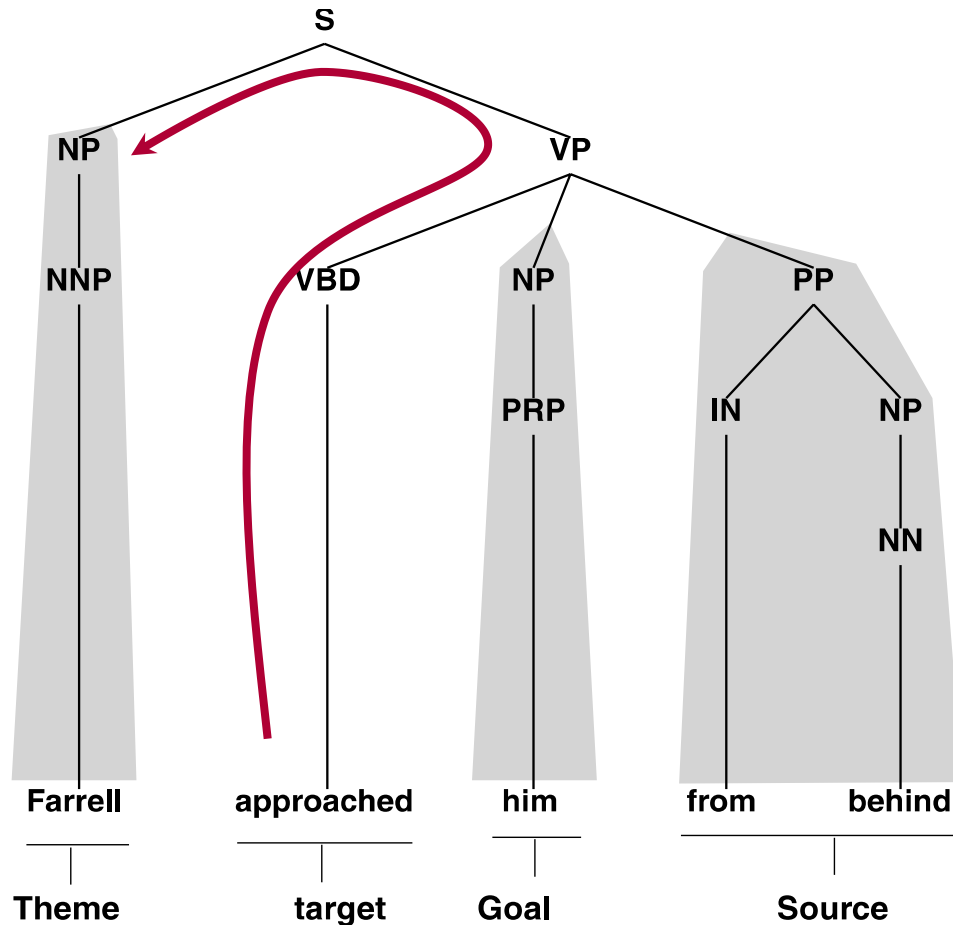
Approach – Features – Parse Tree Path

39



Approach – Features – Parse Tree Path

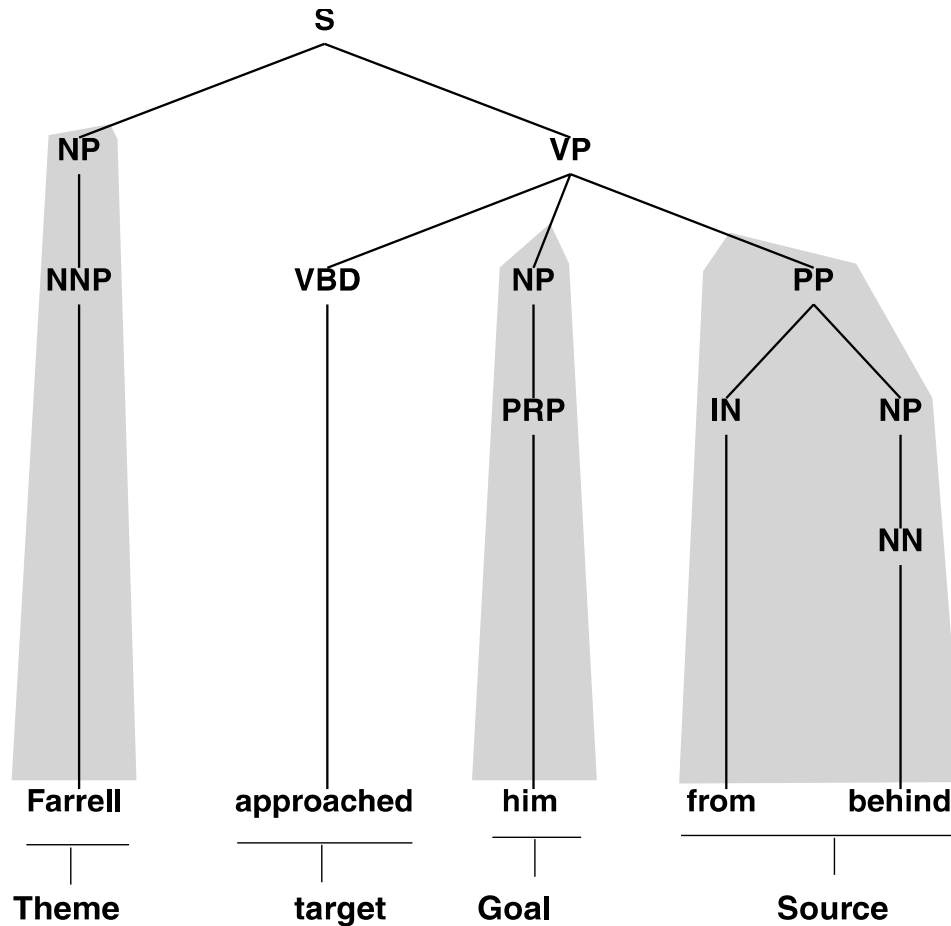
40



- "Farrell" → VBD↑VP↑S↓NP
- ...
- ...

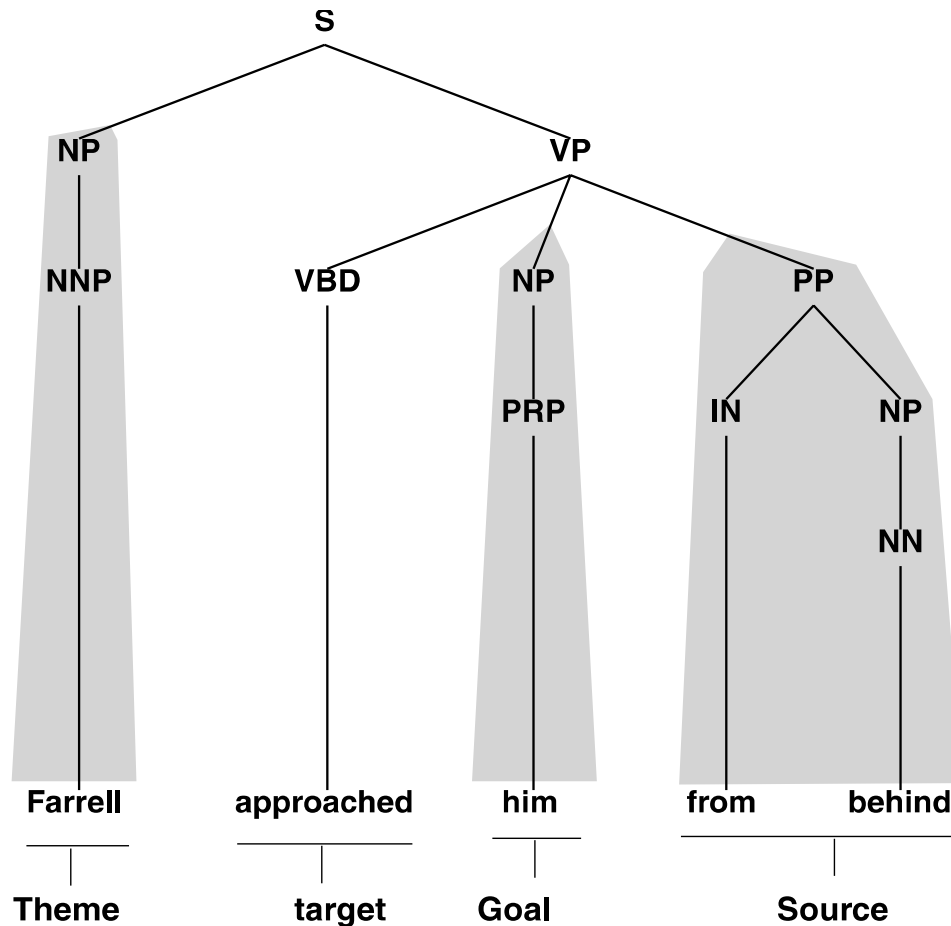
Approach – Features – Position

41



Approach – Features – Position

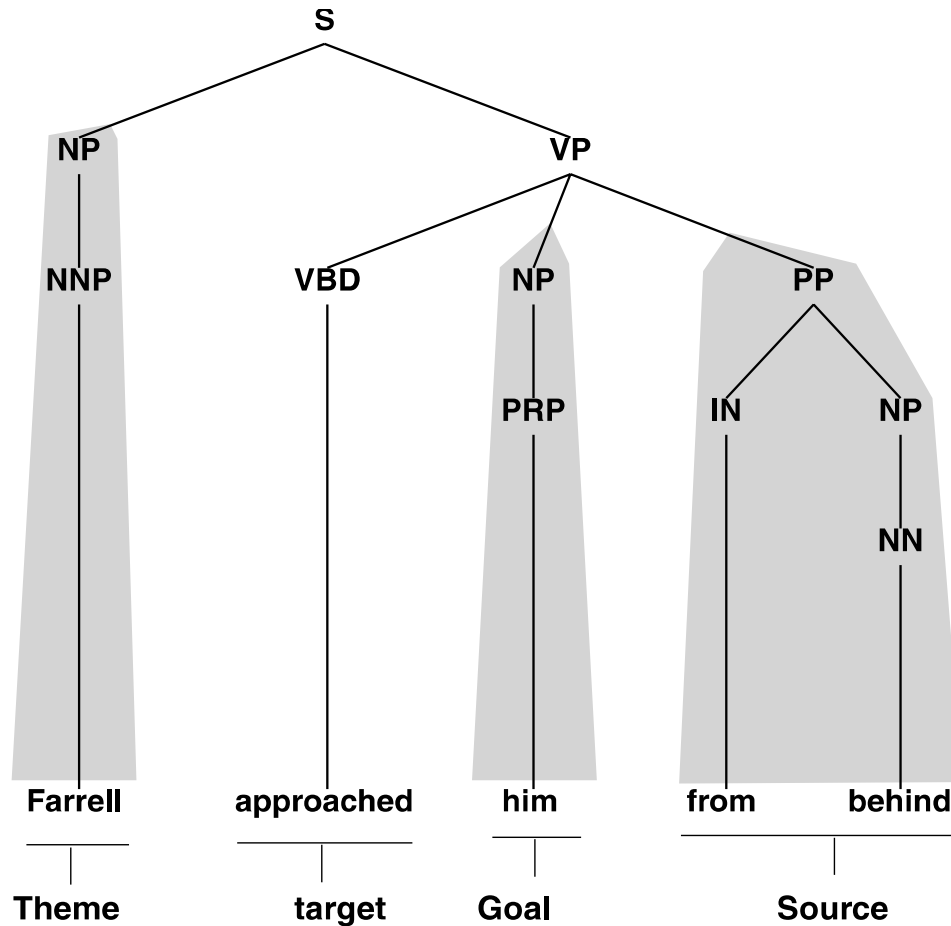
42



- “Farrell” → before
- “him” → behind
- “from behind” → behind

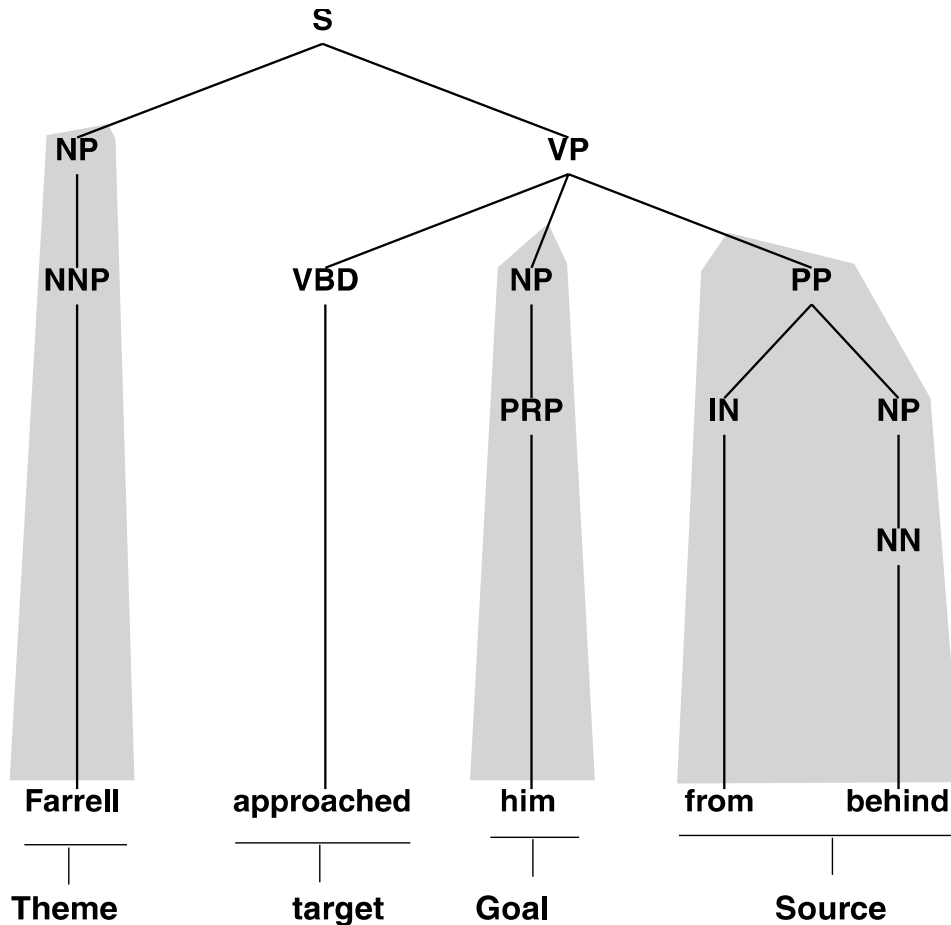
Approach – Features – Voice

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Approach – Features – Voice

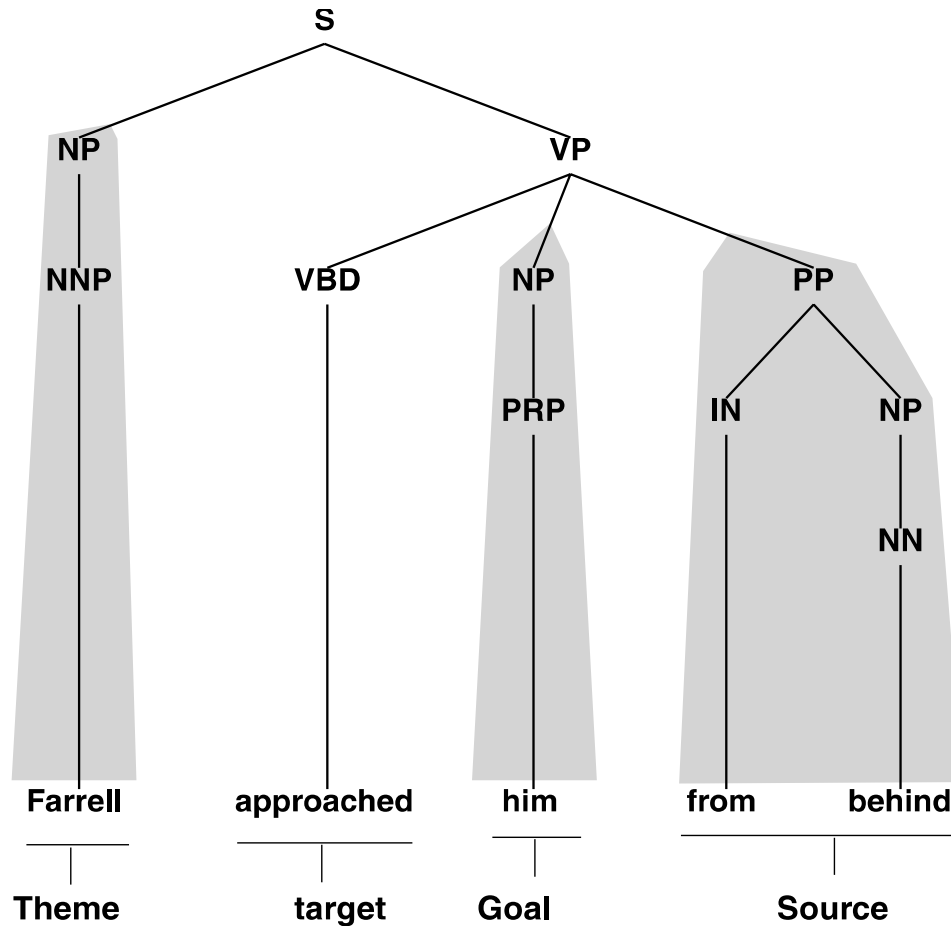
44



- “Farrell” → active
- “him” → active
- “from behind” → active

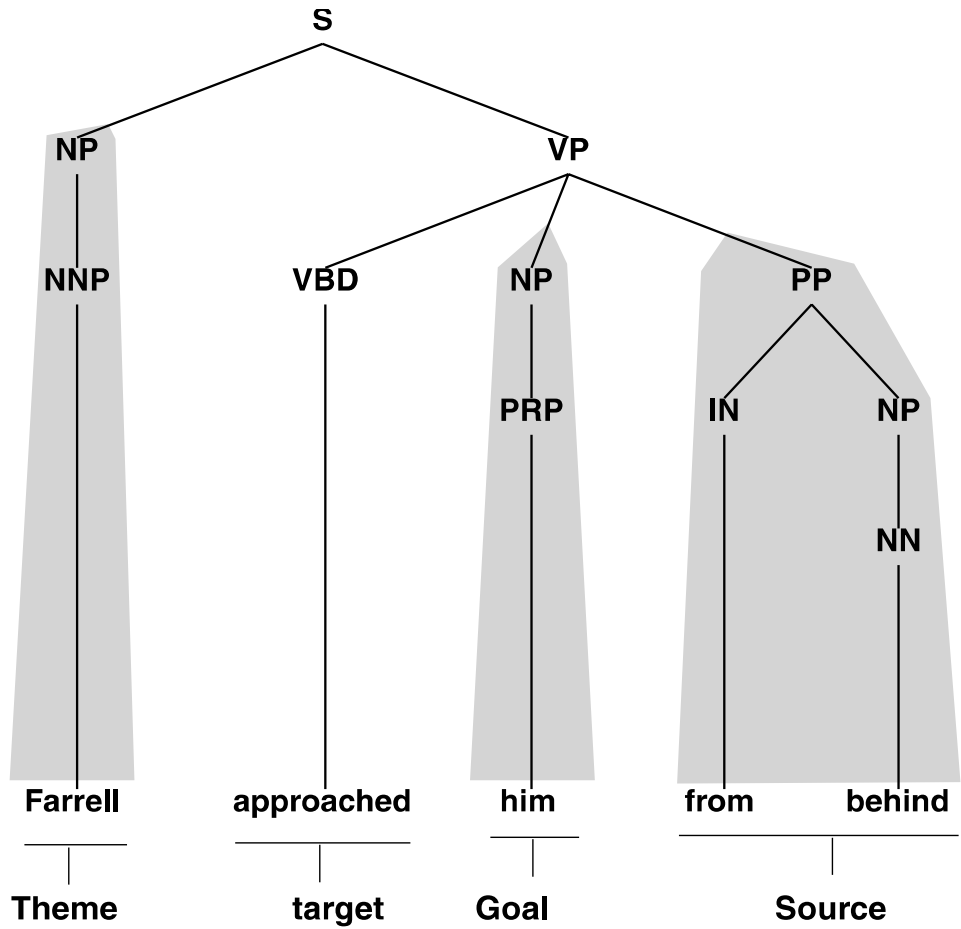
Approach – Features – Head Word

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Approach – Features – Head Word

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- "Farrell" → "Farrell"
- "him" → "him"
- "from behind" → "behind"

Approach – Probability Estimation

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- Probabilities calculated based on features
- Probability:
- Calculation:

Approach – Probability Estimation

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- Probabilities calculated based on features
- Probability: $P(r \mid h, pt, gov, position, voice, t)$
- Calculation:

Approach – Probability Estimation

49

- Probabilities calculated based on features
- Probability: $P(r \mid h, pt, gov, position, voice, t)$
- Calculation:

$$P(r \mid h, pt, gov, position, voice, t) = \frac{\#(r, h, pt, gov, position, voice, t)}{\#(h, pt, gov, position, voice, t)}$$

Approach – Probability Estimation

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$$P(r \mid h, pt, gov, position, voice, t)$$

- Example:
 - How often occurs (“Farrell”, NP, S, before, active, “approached”)?

Approach – Probability Estimation

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$$P(r \mid h, pt, gov, position, voice, t)$$

- Example:
 - How often occurs (“Farrell”, NP, S, before, active, “approached”)?
 - 436 times

Approach – Probability Estimation

52

$$P(r \mid h, pt, gov, position, voice, t)$$

- Example:
 - How often occurs (“Farrell”, NP, S, before, active, “approached”)?
 - 436 times
 - How often does this combination have the role “Theme”?
 - 387 times

Approach – Probability Estimation

53

$$P(r \mid h, pt, gov, position, voice, t)$$

- Example:
 - How often occurs (“Farrell”, NP, S, before, active, “approached”)?
 - 436 times
 - How often does this combination have the role “Theme”?
 - 387 times
 - How often does this combination have the role “Vehicle”?
 - 8 times

Approach – Probability Estimation

54

$$P(r \mid h, pt, gov, position, voice, t)$$

- Example:
 - How often occurs ("Farrell", NP, S, before, active, "approached")?
 - 436 times
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$$P("Theme" \mid "Farrell", NP, S, before, active, "approached") \approx 89\%$$

Approach – Probability Estimation

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$$P(r \mid h, pt, gov, position, voice, t)$$

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 - 387 times
 - How often does this combination have the role "Vehicle"?
 - 8 times

$$P("Theme" \mid "Farrell", NP, S, before, active, "approached") \approx 89\%$$

$$P("Vehicle" \mid "Farrell", NP, S, before, active, "approached") \approx 2\%$$

Approach – Probability Estimation

56

$$P(r \mid h, pt, gov, position, voice, t)$$

- Example:
 - How often occurs ("Farrell", NP, S, before, active, "approached")?
 - 436 times
 - How often does this combination have the role "Theme"?
 - 387 times
 - How often does this combination have the role "Vehicle"?
 - 8 times

$$P(\underline{\textit{Theme}} \mid \textit{Farrell}, NP, S, \textit{before}, \textit{active}, \textit{approached}) \approx 89\%$$

$$P(\textit{Vehicle} \mid \textit{Farrell}, NP, S, \textit{before}, \textit{active}, \textit{approached}) \approx 2\%$$

Approach – Probability Estimation

57

- Problem: features not always available (0 occurrences)
 - Esp. head word: very specific
- $P(r | h, pt, gov, position, voice, t)$ might be too strict

Approach – Probability Estimation

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- Problem: features not always available (0 occurrences)
 - Esp. head word: very specific
- $P(r \mid h, pt, gov, position, voice, t)$ might be too strict
- Solution:
 - Subset of probabilities
 - Different combinations

Approach – Probability Estimation

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- Problem: features not always available (0 occurrences)
 - Esp. head word: very specific
- $P(r | h, pt, gov, position, voice, t)$ might be too strict

- Solution:

- Subset of probabilities
- Different combinations

Distribution	Coverage	Accuracy	Performance
$P(r t)$	100.0%	40.9%	40.9%
$P(r pt, t)$	92.5	60.1	55.6
$P(r pt, gov, t)$	92.0	66.6	61.3
$P(r pt, position, voice)$	98.8	57.1	56.4
$P(r pt, position, voice, t)$	90.8	70.1	63.7
$P(r h)$	80.3	73.6	59.1
$P(r h, t)$	56.0	86.6	48.5
$P(r h, pt, t)$	50.1	87.4	43.8

Approach – Probability Estimation

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- Idea: combine distributions
 - Linear interpolation

$$\begin{aligned}
 P(r \mid \textit{constituent}) &= \lambda_1 P(r \mid t) + \lambda_2 P(r \mid pt, t) \\
 &\quad + \lambda_3 P(r \mid pt, gov, t) + \lambda_4 P(r \mid pt, position, voice) \\
 &\quad + \lambda_5 P(r \mid pt, position, voice, t) + \lambda_6 P(r \mid h) \\
 &\quad + \lambda_7 P(r \mid h, t) + \lambda_8 P(r \mid h, pt, t)
 \end{aligned}$$

Approach – Probability Estimation

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- Idea: combine distributions
 - Linear interpolation

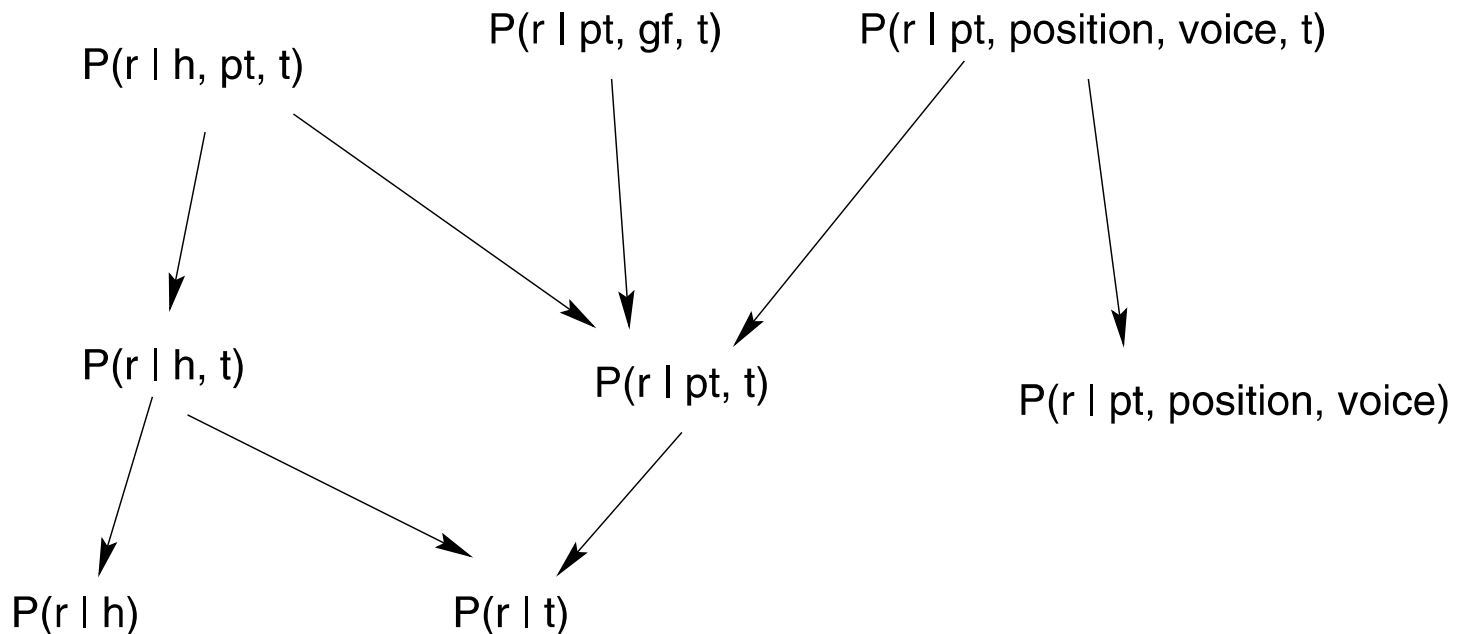
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 &\quad + \lambda_3 P(r \mid pt, gov, t) + \lambda_4 P(r \mid pt, position, voice) \\
 &\quad + \lambda_5 P(r \mid pt, position, voice, t) + \lambda_6 P(r \mid h) \\
 &\quad + \lambda_7 P(r \mid h, t) + \lambda_8 P(r \mid h, pt, t)
 \end{aligned}$$

- 79.5% performance

Approach – Probability Estimation

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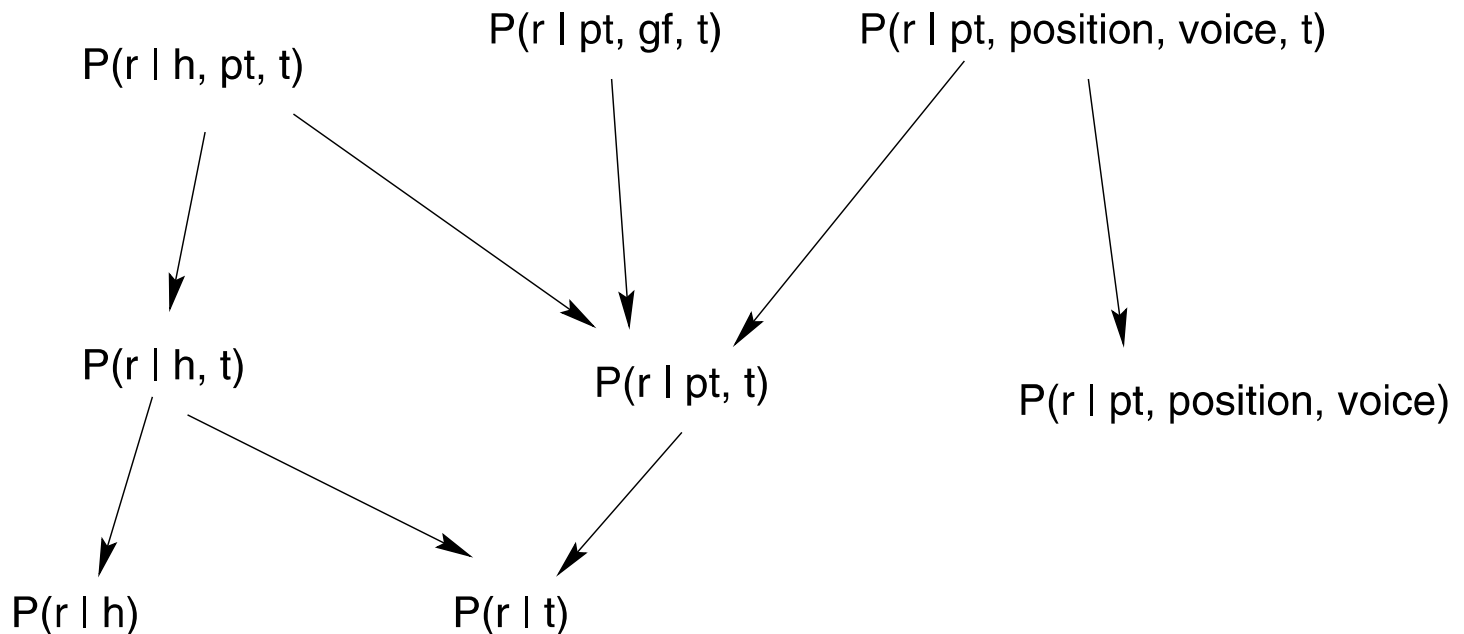
- Idea: combine distributions
 - “Backoff”



Approach – Probability Estimation

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- Idea: combine distributions
 - “Backoff”

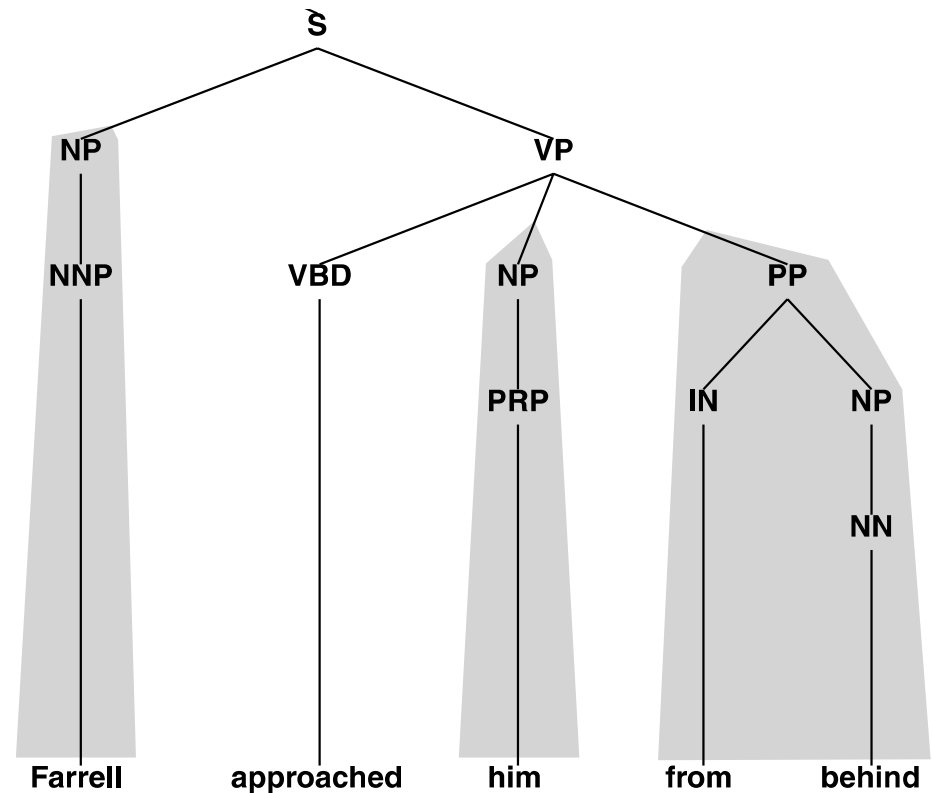


- 80.4% performance

Optional: Boundaries

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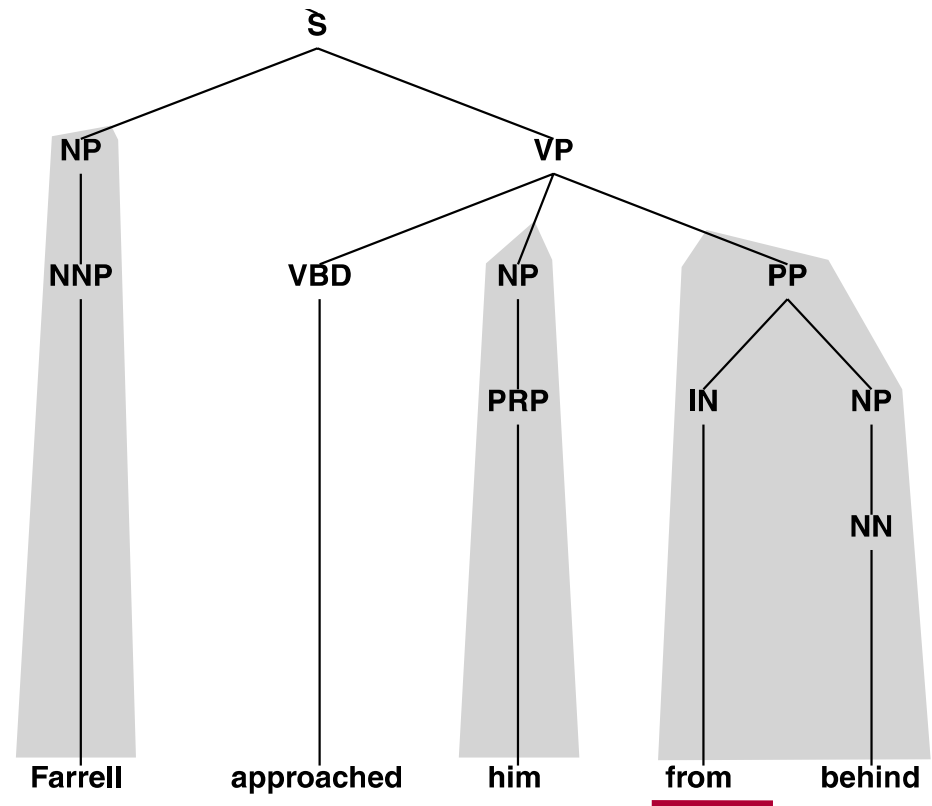
- Additional step before the automatic labeling
- Similar techniques as described before
 - Here: no differentiation among multiple roles → is parse constituent a role or not?
 - Threshold for probability required



Optional: Boundaries

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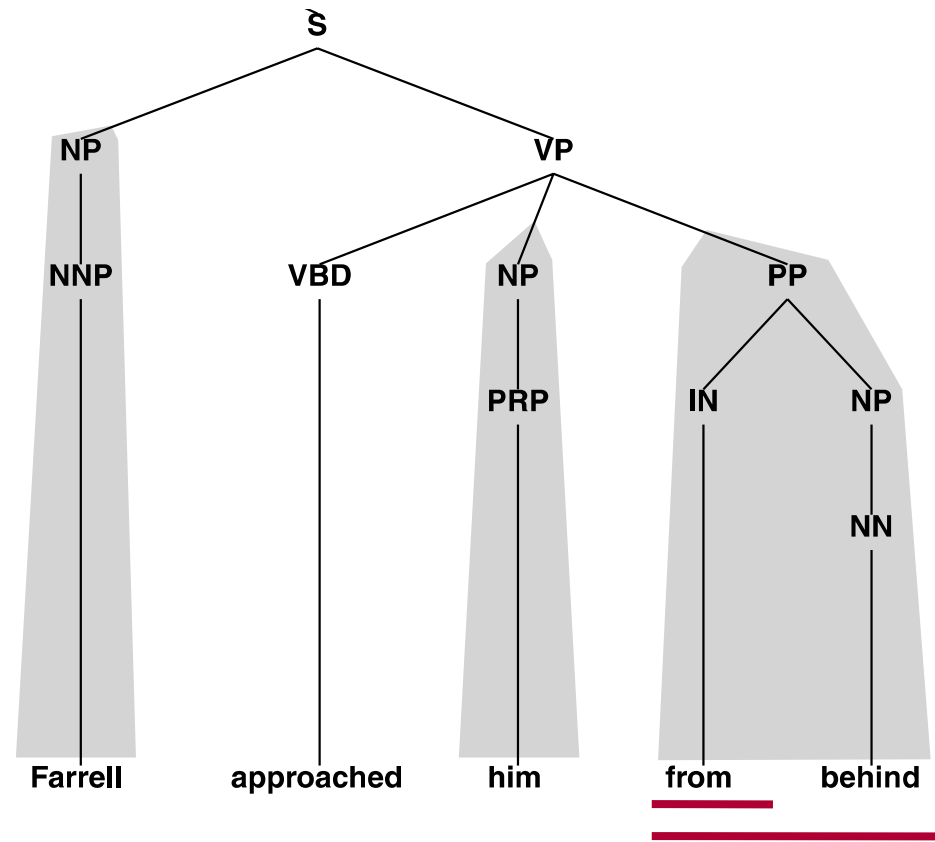
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Optional: Boundaries

66

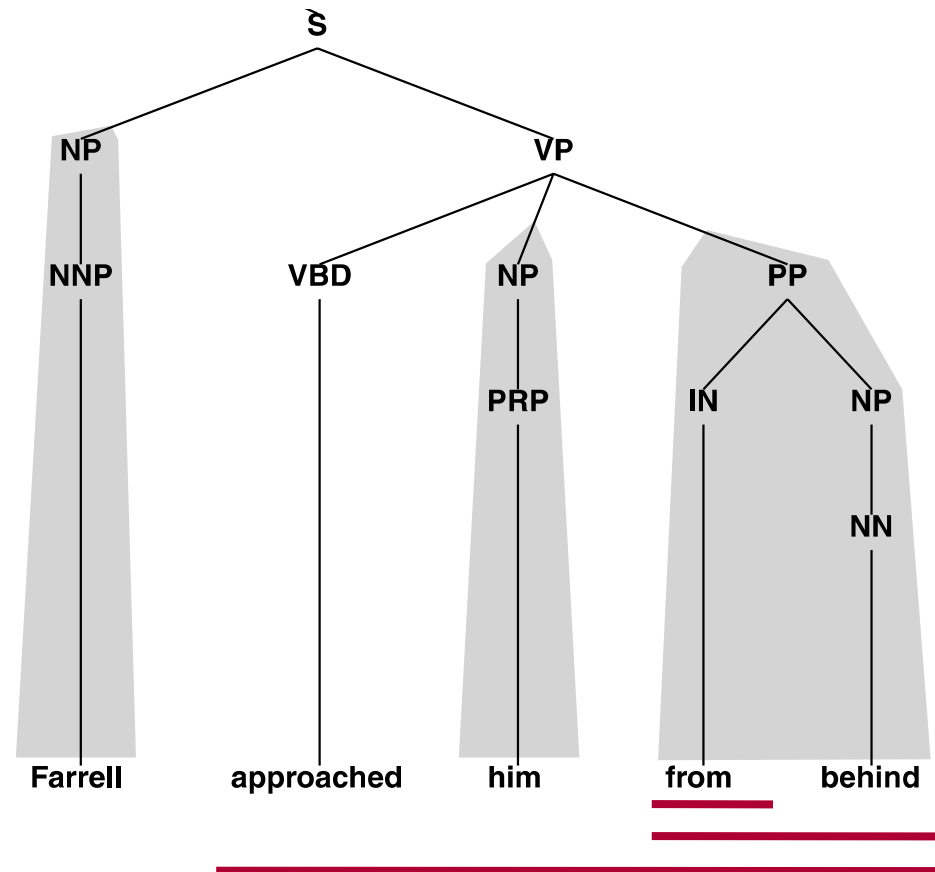
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Optional: Boundaries

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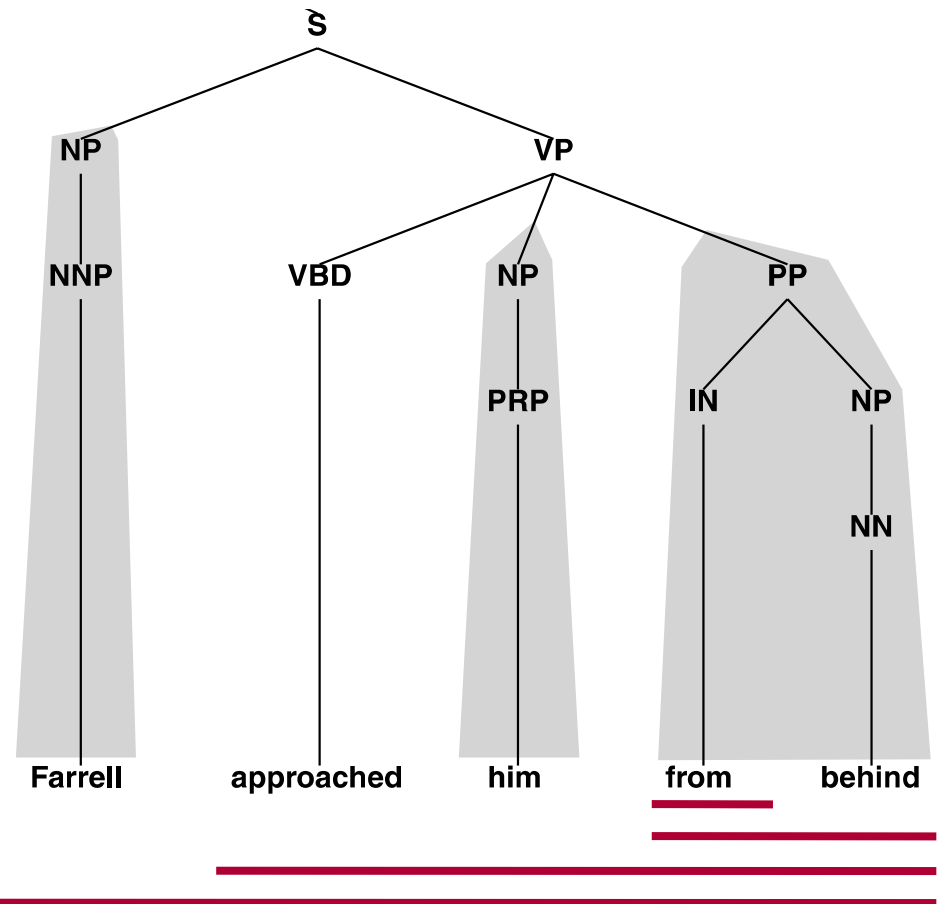
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Optional: Boundaries

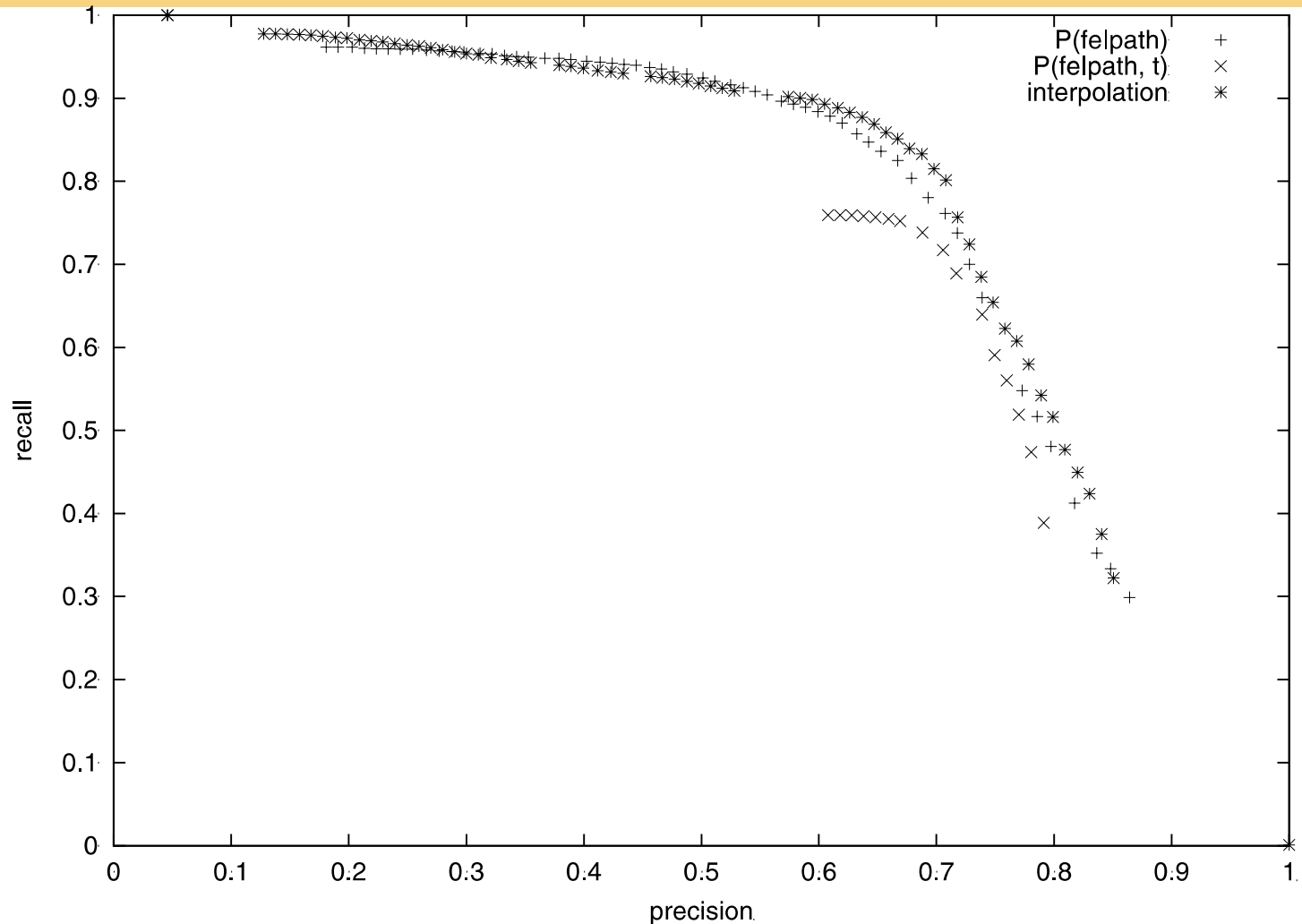
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- Additional step before the automatic labeling
- Similar techniques as described before
 - Here: no differentiation among multiple roles → is parse constituent a role or not?
 - Threshold for probability required



Boundaries – Precision / Recall

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For different recognition thresholds

Discussion

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- With given boundaries → relatively high performance
 - Interpolation of different probability distributions combinations makes sense
- Without boundaries → much lower performance
- Still some tasks open
 - Mostly disambiguation

Discussion

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- With given boundaries → relatively high performance
 - Interpolation of different probability distributions combinations makes sense
- Without boundaries → much lower performance
- Still some tasks open
 - Mostly disambiguation
- Integration into QA system
 - Input: Question + Possible answer sentences (→ disambiguation for frame required)
 - Connection to FrameNet

References

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- Daniel Gildea, Danied Jurafsky, Automatic Labeling of Semantic Roles, Journal of Computational Linguistics, 2002
- Michael Collins, Head-Driven Statistical Models for Natural Language Parsing, Ph.D. dissertation, University of Pennsylvania, Philadelphia, 1999