Data-Driven Demand Learning and Dynamic Pricing Strategies in Competitive Markets

Pricing Strategies & Dynamic Programming

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Outline

• Questions/Support: Market Simulation (Exercise)

• Today: Pricing Strategies & Duopoly Games

Learn about Dynamic Programming

• 1st Exercise: Simulated Markets & Price Reactions

Recall: Rule-Based Price Reaction Strategies

• Idea: (1) Observe competitor prices $\vec{p} + (2)$ Adjust price *a*

• Examples:
$$a(\vec{s}) = a^{(1)}(\vec{p}) := \max\left(c, \min_{k=1,\dots,K} p_k - \varepsilon\right)$$

$$a(\vec{s}) = a^{(n)}(\vec{p}) \coloneqq \max_{a \in A: rank(a, \vec{p}) = n} a$$

$$a(\vec{s}) = a^{(random)}(\vec{p}) \coloneqq if U(0,1) < 0.5 \ then \ a^{(1)}(\vec{p}) \ else \ a^{(2)}(\vec{p})$$

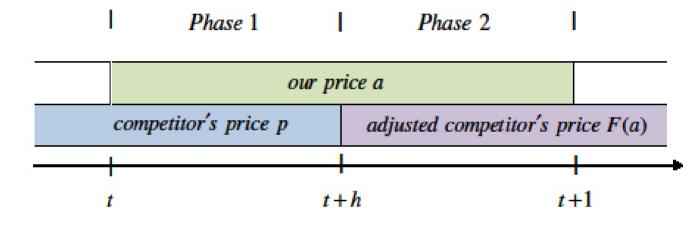
$$a(\vec{s}) = a^{(2bound)}(\vec{p}) \coloneqq \begin{cases} a^{(1)}(\vec{p}) & , p^{\min} \leq \min_{k=1,\dots,K} p_k \leq p^{\max} \\ p^{\max} & , else \end{cases}$$

Duopoly Example

- Assume K=2 sellers. Assume only one feature: price
- Define different price reaction strategies a(p), i.e.,
 if the competitor's current price is p, we adjust our price to a(p)
 Admissible prices are a(p) ∈ {1,2,...,100}
- Let the competitor's response strategy be given by: $p(a) \coloneqq \max(a-1,1)$
- We adjust our prices *a* at times t = 1, 2, 3, ...

The competitor adjusts his prices p at times t = 0.5, 1.5, 2.5, ...

Sequence of Events (Duopoly Example)



• In every interval (t, t+0.5), t = 0, 0.5, 1.0, ..., a sale occurs with probability $1 - \min(a_t, p_t)/100$. With probability $\min(a_t, p_t)/100$ no sale takes place

Duopoly Example

- In every interval (t, t+0.5), t = 0, 0.5, 1.0, ..., a sale occurs with probability $1 \min(a_t, p_t) / 100$. With probability $\min(a_t, p_t) / 100$ no sale takes place
- If a sale takes place the customer chooses either our offer (k=1) or the competitor's offer (k=2) with probability P(k, p) according to Approach I, where p = (p⁽¹⁾, p⁽²⁾) = (a, p), i.e., p⁽¹⁾ = a (we) and p⁽²⁾ = p (competitor)
- Simulate until time T=1000. Start with $a_0 = p_0 = 20$ at time t = 0
- Which strategy a(p) performs best, i.e., maximizes expected revenues?

Goals for Today

- We want to optimally solve the duopoly example
- We have a dynamic optimization problem
- What are dynamic optimization problems?
- How to apply dynamic programming techniques?

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What are Dynamic Optimization Problems?

- How to control a dynamic system over time?
- Instead of a single decision we have a sequence of decisions
- The system evolves over time according to a certain dynamic
- The decisions are supposed to be chosen such that a certain objective/quantity/criteria is optimized
- Find the right balance between short and long-term effects

Examples Please!

Examples

- Inventory Replenishment
- Reservoir Dam
- Drinking at a Party
- Exam Preparation
- Brand Advertising
- Used Cars
- Eating Cake

Task: Describe & Classify

- Goal/Objective
- State of the System
- Actions
- Dynamic of the System
- Revenues/Costs
- Finite/Infinite Horizon
- Stochastic Components

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Classification

Example	Objective	State	Action	Dynamic	Payments
Inventory Mgmt.	min costs	#items	#order	entry-sales	order/holding
Reservoir Dam	provide power	#water	#production	rain-outflow	none
Drinking at Party*	max fun	‰	#beer	impact-rehab	fun/money
Exam Preparation*	max mark/effort	#learned	#learn	learn-forget	effort, mark
Advertising	max profits	image	#advertise	effect-forget	campaigns
Used Cars	min costs	age	replace(y/n)	aging/faults	buy/repair costs
Eating Cake*	max utility	%cake	#eat	outflow	utility
* Finite horizon					

General Problem Description

- What do you want to minimize or maximize (Objective)
- Define the state of your system (State)
- Define the set of possible actions (state dependent) (Actions)
- Quantify event probabilities (state+action dependent) (Dynamics) (!!)
- Define payments (state+action+event dependent) (Payments)
- What happens at the end of the time horizon? (Final Payment)

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Dynamic Pricing Scenario (Duopoly Example)

- We want to sell items in a duopoly setting with finite horizon
- We can observe the competitor's prices and adjust our prices (for free)
- We can anticipate the competitor's price reaction
- We know sales probabilities for various situations
- We want to maximize total expected profits

Problem Description (Duopoly Example)

- Framework: t = 0, 1, 2, ..., T Discrete time periods
- State: s = p Competitor's price
- Actions: $a \in A = \{1, ..., 100\}$ Offer prices (for one period of time)
- Dynamic: P(i, a, s)

Probability to sell i items at price a

• Payments: $R(i, a, s) = i \cdot a$ Real

Realized profit

• New State: $p \xrightarrow{\Gamma(i,a,s)} F(a)$

State transition / price reaction F

• Initial State: $s_0 = p_0 = 20$

Competitor's prices in t=0

Problem Formulation

• Find a *dynamic pricing strategy* that

maximizes total expected (discounted) profits:

•
$$\max E\left[\sum_{\substack{t=0 \ discount \ factor}}^{T} \underbrace{\delta_{i_t \ge 0}^t}_{\substack{i_t \ge 0 \ probability \ to \ sell \ i_t \ items \ sales \ price}}_{at \ price \ a_t \ in \ situation \ S_t} \cdot \underbrace{i_t \cdot a_t}_{price \ a_t \ in \ situation \ S_t}}\right] \left| \underbrace{S_0 = S_0}_{initial \ state}\right], \ 0 < \delta \le 1$$

• What are admissible policies?

Answer: Feedback Strategies

• How to solve such problems?

Answer: Dynamic Programming

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Solution Approach (Dynamic Programming)

• What is the **best expected value** of having the chance to sell . . .

"items from time t on starting in market situation s"?

- Answer: That's easy $V_t(s)$! ?????
- We have renamed the problem. Awesome. But that's a solution approach!
- We don't know the "Value Function V", but V has to satisfy the relation Value (state to drew) = Rest expected (supplies drew + Value (state to measure))

Value (state today) = Best expected (profit today + Value (state tomorrow))

Solution Approach (Dynamic Programming)

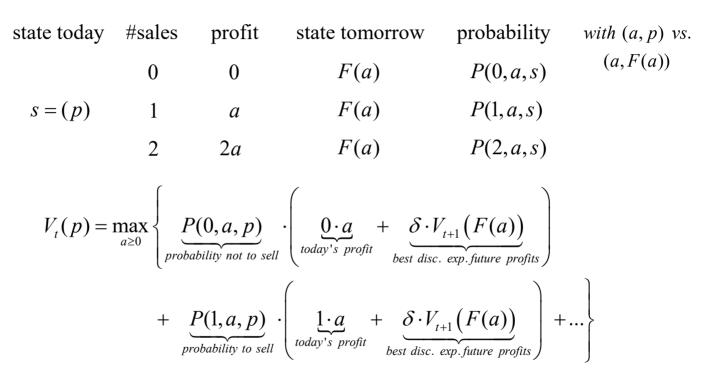
- Value (state today) = Best expected (profit today + Value (state tomorrow))
- Idea: Consider the transition dynamics within one period What can happen during one time interval?

state today	#sales	profit	state tomorrow	probability	with (a, p) vs.
	0	0	F(a)	P(0,a,s)	(a,F(a))
s = p	1	а	F(a)	P(1,a,s)	
	2	2a	F(a)	P(2,a,s)	

• What does that mean for the value of state s = p, i.e., $V_t(s) = V_t(p)$?

Bellman Equation





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Optimal Solution

• We finally obtain the Bellman Equation:

$$V_t(p) = \max_{a \ge 0} \left\{ \sum_{i \ge 0} \underbrace{P(i, a, p)}_{\text{probability}} \cdot \left(\underbrace{i \cdot a}_{\text{today's profit}} + \underbrace{\delta \cdot V_{t+1}(F(a))}_{\text{best disc. exp. future profits of new state}} \right) \right\}$$

- Ok, but why is that interesting?
- Answer: Because $a_t^*(p) = \underset{a \in A}{\operatorname{arg\,max}} \{...\}$ is the optimal policy
- Ok! Now, we just need to compute the Value Function!

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How to solve the Bellman Equation?

• Using the terminal condition $V_T(p) \coloneqq 0$ for time horizon T (e.g., 1000) We can compute the value function *recursively* $\forall t, p$:

$$V_{t}(p) = \max_{a \ge 0} \left\{ \sum_{i \ge 0} \underbrace{P(i, a, p)}_{\text{probability}} \cdot \left(\underbrace{i \cdot a}_{\text{today's profit}} + \underbrace{\delta \cdot V_{t+1}(F(a))}_{\text{best disc. exp. future profits of new state}} \right) \right\}$$

• The optimal strategy $a_t^*(p)$, t = 1,...,T, p = 1,...,100,

is determined by the arg max of the value function

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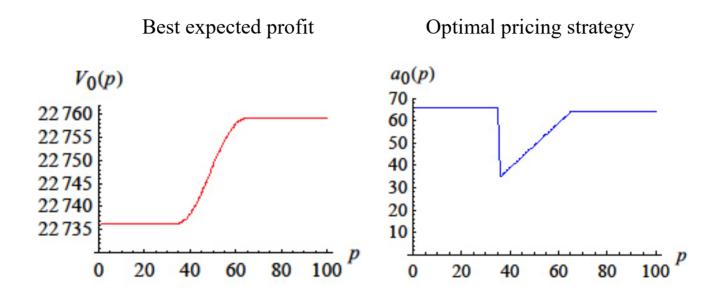
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- The optimal strategy $a_t^*(p)$, t = 1,...,T, p = 1,...,100, is determined by the arg max of the value function
- In Pseudo-Code:

param V{t in 0..T,p in A}:= if t<T then max {a in A}
sum{i in I} P[i,a,p] * (i*a + delta * V[t+1,F[a]]);</pre>

Optimal Pricing Strategy of the Duopoly Example





Infinite Horizon Problem

•
$$\max E\left[\sum_{t=0}^{\infty} \underbrace{\underbrace{\delta}_{i_t \ge 0}^{t}}_{factor} \cdot \left(\sum_{i_t \ge 0} \underbrace{\underbrace{P(i_t, a_t, S_t)}_{probability \ to \ sell \ i_t} + \underbrace{S_t}_{sales \ price}}_{sales \ price}\right) \middle| \underbrace{\underbrace{S_0 = S_0}_{initial \ state}}_{initial \ state}\right], \ \underline{0 < \delta < 1}$$

- Will the value function be time-dependent?
- Will the optimal price reaction strategy be time-dependent?
- How does the Bellman equation look like?

Solution of the Infinite Horizon Problem

•
$$V^*(p) = \max_{a \ge 0} \left\{ \sum_{i \ge 0} \underbrace{P(i, a, p)}_{\text{probability}} \cdot \left(\underbrace{i \cdot a}_{\text{today's profit}} + \underbrace{\delta \cdot V^*(F(a))}_{\text{disc. exp. future profits of new state}} \right) \right\}$$

- Approximate solution: Finite horizon approach (value iteration)
- For "large" *T* the values $V_0(p)$ converge to the exact values $V^*(p)$
- The optimal policy $a^*(p)$, p = 1,...,100, is determined by the arg max of the last iteration step, i.e., $a_0(p)$



Exact Solution of the Infinite Horizon Problem

•
$$V^*(p) = \max_{a \ge 0} \left\{ \sum_{i \ge 0} \underbrace{P(i, a, p)}_{\text{probability}} \cdot \left(\underbrace{i \cdot a}_{\text{today's profit}} + \underbrace{\delta \cdot V^*(F(a))}_{\text{disc. exp. future profits of new state}} \right) \right\}, \ p \in A$$

- We have to solve a system of nonlinear equations
- Solvers can be applied, e.g, MINOS (see NEOS Solver)
- In Pseudo-Code:

subject to NB {p in A}: V[p] = max {a in A}
sum{i in I} P[i,a,p] * (i*a + delta * V[F[a]]); solve;

Questions?

- State
- Action
- Events
- Dynamics & State Transitions
- Recursive Solution Principle
- General concept applicable to other problems

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1st Exercise – Simulated Markets & Price Reactions

- Study our market simulation notebook
- Modify the arrival stream of interested customers
- Modify the customer behaviour (scoring weights)
- Modify the competitors' reaction strategies
- Bonus (Dynamic Programming): Solve duopoly example with finite horizon

Overview

2	April 24	Customer Behavior
3	April 30	Pricing Strategies, 1 st Homework (market simulation)
4	May 8	Demand Estimation, 2 nd Homework (demand learning)
5	May 15	Introduction Price Wars Platform
6	May 22	Warm up Platform Exercise (in Groups)
7	May 29	Dynamic Pricing Challenge / Projects
8	June 5	no Meeting
9	June 12	Workshop / Group Meetings
10	June 19	Presentations (First Results)
11	June 26	Workshop / Group Meetings
12	July 3	Workshop / Group Meetings
13	July 10	no Meeting
14	July 17	Presentations (Final Results), Feedback, Documentation (Aug/Sep)